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Virtual Prototyping for Rapid Product Development

S.H. Choi and H.H. Cheung

*Department of Industrial and Manufacturing Systems Engineering
The University of Hong Kong
Hong Kong SAR
China*

1. Introduction

Intensifying globalization and market competition has been driving the manufacturing industry to compete on continual reduction in lead-time and cost of product development while assuring high quality and wide varieties. Conventional manufacturing processes are, however, no longer sufficient to speed up product development to meet ever-increasing diversities of customer demands, stringent cost control, and complexity of new products.

In recent years, various technologies have been developed to facilitate rapid product development. Among these technologies, virtual prototyping (VP) and virtual manufacturing (VM) may be regarded as important technological advancements. VP and VM integrate virtual reality (VR) simulation techniques with design and manufacturing processes to fabricate digital prototypes for subsequent stereoscopic visualisation, validation and optimisation of product designs, as well as for evaluation of product assemblability and producibility.

As shown in Figure 1, VP and VM together close a design-simulate-improve loop, in which design and production simulation techniques are integrated for visualisation and optimisation of a complete product development process in a VR environment to enhance product maturity. While VP focuses on the design process that digitally fabricates prototypes for evaluation and improvement of a product design, VM facilitates validation and optimisation of all subsequent stages of the downstream manufacturing process, such as facility layout, product assembly, and production scheduling.

This design-simulate-improve loop can be iterated effectively and quickly to shorten the product design and development cycle without incurring much additional costs. Indeed, manufacturers can test all stages of product development in a virtual environment. As such, they will be able to “get it right the first time” to enhance product maturity substantially at an earlier stage, and to deliver quality products to market on time and within budget.

This chapter presents an integrated VP system for digital fabrication of complex prototypes to facilitate rapid product development. The VP system comprises a suite of software packages for multi-material layered manufacturing (MMLM) processes, including multi-toolpath planning, build-time estimation and accuracy analysis, integrated with semi-immersive desktop-based and full-immersive CAVE-based VR technology for digital

fabrication and subsequent visualisation of product prototypes. The desktop-based VR system creates a semi-immersive virtual environment for stereoscopic visualisation and quality analysis of a product design. It is relatively cost-effective and easy to operate, but its users may be distracted by environmental disturbances that could possibly diminish their efficiency of product design evaluation and improvement. To alleviate disturbance problems, the CAVE-based VR system provides an enclosed room-like virtual environment that blocks out most disturbances, making it possible for a design team to fully concentrate and collaborate on their product design work.

Fig. 1. Integration of virtual prototyping (VP) with virtual manufacturing (VM) for rapid product development

The VP system enhances collaboration and communication between designers working on product development. It provides tools for simulation and visualisation to analyse and improve the design of a product and its fabrication processes. Through simulations, assessment and modification of a product design can be iterated without incurring much manufacturing and material costs of prototypes. Hence, key factors such as product shape

and manufacturability that may affect the product maturity and profitability can be optimised quickly. Moreover, the resulting product design can be sent via the Internet to customers for comments or marketing purposes. The VP system therefore facilitates rapid product development and helps reduce time-to-market and cost considerably.

This chapter will first review the background and technologies related to development of VP. The architecture and technical considerations of the proposed VP system will then be discussed in detail. Case studies involving digital fabrication of complex, multi-material objects will be presented to illustrate possible applications of the VP system for product design and development.

2. Review of related works

2.1 Layered Manufacturing and multi-material layered manufacturing

Layered Manufacturing (LM), also called Rapid Prototyping (RP), is an additive manufacturing process that produces a physical prototype from a 3D CAD model layer by layer. The model can be generated from CAD designs or surface data captured from CT, MRI and laser 3D scanning.

LM systems are widely adopted in manufacturing and medical applications to save cost and time. Manufacturers use LM technology to produce prototypes of products for design evaluation, and as master patterns for production tools.

Lopez and Wright (2002) studied the impact of LM on product design and development processes. The study shows that LM may help shorten the product development cycle drastically and enable designers to incorporate mechanical and ergonomic features into new products easily. Tennyson et al. (2006) did a project to promote solid modelling and RP technologies to Idaho's rural manufactures in USA for rapid product development. The result of the project illustrates that the manufacturers adopting such technologies can enhance their capability to bring products to the marketplace more rapidly and with greater success.

Fig. 2. A multi-material bicycle prototype fabricated by Connex500™ multi-material 3D printing system (Object, 2011b)

Multi-material layered manufacturing (MMLM), which evolves from the LM technology, refers to a process of fabricating a prototype or an assembly product consisting of more than

one component material from CAD models with material information, layer by layer. Due to the additive characteristics of LM processes, multiple materials can be selectively deposited on the related slice contours.

Object (2011a) created a Connex500™ multi-material 3D printing system that jets multiple model materials simultaneously to fabricate multi-material parts or assemblies with different mechanical or physical properties, all in a single build. Figure 2 shows a printed multi-material bicycle prototype (Object, 2011b).

2.2 Virtual prototyping

VP is an innovative and powerful virtual simulation tool for facilitating rapid product development (Kerttula and Tokkonen, 2001; Mujber et al., 2004), and it has been successfully used in ship-building and car industries (Kim et al., 2002; Wöhlke and Schiller, 2005).

It is a process of using virtual or digital prototypes and simulation techniques, often in a VR environment with innovative input and 3D stereoscopic output, to evaluate and improve a product design and to facilitate validation of its planning and manufacturing processes (Bochenek and Ragusa, 1998; Gomes and Zachmann, 1999; Kerttula and Tokkonen, 2001; Mujber et al., 2004; Patel et al., 2006; Weyrich and Drews, 1999).

Through simulations, key factors such as the shape and the manufacturability of a product may be optimised without committing much to prototypes and tooling. Indeed, virtual simulation reduces the need for physical prototypes and hence minimizes tooling cost and material waste, and it allows manufacturers to “get it right the first time” and helps them deliver quality products to market on time and within budget.

However, the current virtual simulation technique, which often adopts either semi- or full-immersive VR, is not without limitations, particularly with respect to the sense of immersion.

Bochenek and Ragusa (1998) pointed out that it is important to appropriately select a VR system for facilitating product design and development processes. They investigated the use of four commercial VR display systems and found that the sense of immersion plays an important role in improving the design review practices, and that a higher sense of immersion will have better improvement.

In general, semi-immersive VR systems (single-screen or desktop-based) are relatively easy to use, affordable, and of good resolution, though their users tend to be susceptible to environmental distractions. On the other hand, full-immersive VR systems (multi-screen or CAVE-based) can generate a relatively higher sense of immersion that facilitates user interaction and collaboration, but they are generally more expensive, of less resolution and poor portability, and needs special space requirements (Fairen et al. 2004; Hoffmann et al. 2006; Mujber et al. 2004). Hence, it is worthwhile to combine the good features of both semi- and full-immersive VR to enhance the versatility and effectiveness of virtual simulation at affordable cost.

Therefore, it is desirable to develop a VP system for evaluation of product designs and digital fabrication of multi-material prototypes either in a semi-immersive environment or in a full-immersive, disturbance-free environment to facilitate rapid product development.

3. The proposed virtual prototyping system

The proposed VP system consists mainly of a suite of software packages to facilitate and simulate various stages of an MMLM process, including colour STL modelling, slicing,

topological hierarchy sorting of slice contours for subsequent process planning, multi-toolpath planning and generation, and build-time estimation (Choi & Cheung, 2005a, 2005b, 2006 & 2007). In particular, these packages are integrated with a set of control modules and VR graphics kernels that drive both desktop- and CAVE-based VR platforms to create semi- and full-immersive visualisation of the MMLM process at the user's choice.

With the proposed VP system, designers can fabricate digital multi-material prototypes, in lieu of costly physical ones, to evaluate product designs and visualise the influences of critical process parameters, such as build-direction, layer thickness, and hatch space, on the MMLM process. The resulting digital prototypes can be sent via the Internet to customers to solicit comments, while the process parameters can be used for optimal fabrication of physical prototypes. This approach can considerably reduce the number of costly physical prototypes needed for rapid product development. As a result, the associated manufacturing overheads and product development time can be reduced substantially, because digital prototypes are mostly used and there is no worry about the cost and the quality of physical prototypes.

Using the resulting set of optimal process parameters, physical prototypes of desirable quality can be made quickly and economically for detailed design evaluation. The physical prototypes can also be used as master patterns for making tools needed by conventional manufacturing processes, such as CNC machining, silicon rubber moulding and injection moulding, for mass production of the final products.

Furthermore, the VP system would be particularly useful for small-batch production of customised products, which cannot be produced with conventional processes economically. Recently, LM has been widely explored for direct manufacture of customised products. It is envisaged that when LM becomes viable for direct manufacture of customised products, it will be vital to validate the accuracy and quality of prototypes before committing to physical fabrication. Therefore, the VP system would be a practical simulation tool for rapid product development.

Figure 3 shows the flow of the VP system. Firstly, a product model created by CAD or captured by a CT/MRI scanner or a laser digitiser is converted into STL format, which is the industry de-facto standard. As STL is monochrome or single-material, an in-house package is used to paint STL models, with each colour representing a specific material.

Secondly, a few steps are undertaken to prepare for subsequent simulation of the MMLM process and visualisation of the resulting digital prototypes: (a) slice the colour STL model into a number of layers of a predefined thickness. If the LM machine supports variable layer thickness, the STL model may be sliced with an adaptive slicing algorithm to increase fabrication efficiency. The resultant layer contours and material information are stored in a modified Common Layer Interface (CLI) file; (b) sort the slice contours with a contour sorting algorithm to establish explicit topological hierarchy; (c) based on the hierarchy information, multi-toolpath planning algorithms are used to plan and generate multi-toolpaths by hatching the slice contours with a predefined hatch space. The hatch vectors are stored in the modified CLI file for fabrication of digital prototypes and build-time estimation.

Thirdly, a versatile VR simulation system is used for digital fabrication of multi-material prototypes. It allows users to choose either a desktop- or CAVE-based VR platform to create a semi- or full-immersive virtual environment, respectively, for stereoscopic visualisation and quality analysis of the resulting digital prototypes, with which product designs can be reviewed and improved efficiently.

Fig. 3. The flow of the proposed VP system

A suite of algorithms for LM process planning, such as slicing, choice of build-direction, model orientation and layer thickness, generation of sequential and concurrent multi-toolpaths, and build-time estimation, are incorporated in the proposed VP system. The details of these algorithms have been presented in (Choi & Samavedam, 2001 & 2003; Choi & Chan, 2002; Choi & Kwok, 2002 & 2004; Choi & Cheung, 2005a, 2005b, 2006 & 2007).

This chapter focuses on the development of the VR system. In particular, it addresses the enhancement of versatility and effectiveness of virtual simulation for product design and digital fabrication of multi-material prototypes at affordable cost. The following section describes the desktop- and the CAVE-based VR platforms in detail.

3.1 The desktop-based VR system

The desktop-based VR system consists mainly of a suite of software packages for stereoscopic visualisation of product designs and optimisation of MMLM processes. The software interfaces with commercial desktop-based VR hardware to display a model for stereoscopic visualisation. Using a desktop monitor, which is relatively small but highly portable, a user wears a pair of active shutter glasses that generate stereoscopic feelings by synchronising with the display device to switch on and off the images to the left eye and the right eye alternatively.

This creates a semi-immersive VR environment in which a designer can stereoscopically visualise product designs and perform quality analysis. If a much larger display is needed, a pair of LCD projectors with a large screen as in Figure 4 can be used. The designer wears a pair of oppositely polarised glasses that filter the polarised images for the left eye and the right eye respectively. With this wall-sized screen, a group of designers can participate in stereoscopic visualisation and collaborative review of product designs in the semi-immersive VR environment. This indeed improves exchange of ideas among a design team.

Fig. 4. LCD projectors with a screen for semi-immersive VR display

In addition, the software consists of a Product Viewer module and a Virtual Prototype Fabrication module, based on the WorldToolkit (WTK) graphic libraries, for simulation of MMLM processes.

The Product Viewer module displays a colour product model in a semi-immersive VR environment, in which a small group of designers can work together to study and improve the product design.

The Virtual Prototype Fabrication module can then fabricate digital multi-material prototypes of the product. A dixel-based approach is adopted for digital fabrication of prototypes (Choi & Samavedam, 2001). A dixel is a hatch vector representing the path that a tool has to follow within a contour to build a portion of a layer. By building a volume of a specific height and a width around a dixel, a strip of material is represented. Hence, rectangular solid strips are laid to form a layer, which is subsequently stacked up to form a prototype.

During a digital fabrication process, a designer can observe how a product prototype, such as a toy assembly in figure 5, is fabricated. When it is finished, the resulting digital multi-material prototype can be studied using the utilities provided to visualise the quality of the prototype that the LM machine will subsequently deliver. The designer can navigate around the internal and opaque structures of the prototype to investigate the design. Besides, the colour STL model can be superimposed on its digital prototype for comparison, with the maximum and the average cusp highlighted to indicate the dimensional deviations. A tolerance may be set to highlight locations with deviations beyond the limit. The designer may thus identify and focus on the parts that would need modifications. To improve the accuracy and the surface quality of some specific features of the prototype, the process parameters, such as the build-direction, the model orientation, the layer thickness, and the hatch space, may be tuned accordingly.

Fig. 5. Two perspectives of a toy assembly prototype

After the visualisation process, the colour STL model of the toy assembly is sliced, for example, into 60 layers with a thickness of 3.310 mm, because most current LM machines support only uniform layer thickness during a prototype fabrication process. If the LM machine to be simulated supports variable layer thickness, the model may be instead sliced with an adaptive slicing algorithm. The resulting layer contours are then sorted to establish the topological hierarchy for generation of multi-toolpaths with a hatch space of 0.100mm. Subsequently, the Virtual Prototype Fabrication module fabricates a digital prototype by

depositing the rectangular solid strips one by one at an appropriate z-height, as shown in Figure 6.

Fig. 6. Digital fabrication of a multi-material toy assembly

The resulting virtual prototype of the toy assembly can be manipulated for visual inspection, as in Figure 7. Furthermore, it can be superimposed on its STL model to

highlight the surface texture and the dimensional deviations. The system also calculates the cusp heights to evaluate the overall dimensional deviations. In this example, the average and the maximum cusp heights are 2.001mm and 0.992mm, respectively. Suppose that any deviations more than 1.990mm are considered unacceptable, the designer may choose to highlight the areas which are out of the design limit for subsequent investigation of these critical features. Excessive deviations are highlighted with red or green pins. The red pins point to the maximum deviations whereas the green ones point to unacceptable deviations.

If unsatisfactory deviations are located at important parts of the model, the designer may choose either to change the model orientation to shift the deviations or to reduce the layer thickness and the hatch space to improve the accuracy. When it is necessary to assess detailed assembly fitness of the various parts of the toy, the parts can be stored as individual STL models for quality analysis and digital fabrication.

Digital fabrication of a prototype can be repeated until a set of acceptable process parameters are obtained. Subsequently, physical prototypes of all parts are produced and assembled to form a complete toy prototype. Furthermore, the physical prototypes can be processed and used as master patterns to make tools for mass production of the product.

Fig. 7. Superimposition of the toy assembly prototype on its STL model

Therefore, the proposed desktop-based VR system is an easy-to-use and cost-effective tool for visualisation and digital fabrication of multi-material prototypes to facilitate review and

improvement of product designs. However, the semi-immersive VR environment may be susceptible to environmental disturbances, diminishing the designers’ true feeling and concentration and hence their efficiency in the design process. To address this problem, the level of immersion is enhanced by integrating the VP system with a CAVE-based VR system with multiple screens to provide a full-immersive virtual environment for vivid stereoscopic visualisation and interaction in a natural way. As such, a design team can fully immerse in exploration, study, and improvement of a product design, including assemblies, sub-assemblies, and components, well before they ever exist physically in reality. Hence, the time and cost of product development can be further reduced.

3.2 The CAVE-based VR platform

The CAVE-based VR platform consists of a cubicle of three walls on a floor. An immersive virtual environment is created by projecting stereoscopic images on three 10ft x 8ft screens on the walls, namely the front, the right, and the left, respectively, and on a 10ft x 10ft screen on the floor. Figure 8a and Figure 8b show respectively the architecture and the physical construction of the PC-based CAVE system, called imseCAVE, in the IMSE Department at the University of Hong Kong.

Fig. 8a. The architecture of the imseCAVE

Each projection screen has a reflector and two LCD projectors controlled by two related PCs. The LCD projectors are specially designed with polarising lenses to produce high-resolution stereoscopic images. A VR engine, consisting of a cluster of network PCs, coordinates the projectors to project images on the related screens to create an immersive virtual

environment. This configuration forms a relatively low-cost, configurable, and flexible CAVE-based VR system, which can be conveniently integrated to form the proposed versatile VP system to facilitate product development. The hardware is controlled by a software package, which can be separated into three layers, as shown in Figure 9.

Fig. 8b. Physical construction of the imseCAVE

Fig. 9. Software architecture of the PC cluster-based CAVE system

The bottom layer includes basic system software and hardware, such as Windows XP OS and graphics kernel for control of the PC network, interface devices, and projectors. The middle layer is a PC cluster-based library that coordinates all operations of the CAVE system. It synchronises all the devices to create correct perspective for each screen, keeps track of which screens are in use, and provides the applications with the current states of all

the CAVE elements. It consists of three sub-systems: (i) I/O device sub-system for controlling I/O devices; (ii) display subsystem for projecting images on the corresponding screens; and (iii) the network subsystem for keeping communication and synchronisation between all clustering PCs.

The top layer is a package of tailor-made application programs, developed with the PC cluster-based CAVE library, for immersive visualisation and simulation in the CAVE system. This application package is implemented in an object-oriented programming tool, called the Virtools Dev, and its add-on library, called Virtools VR Pack (Virtools, 2006). The Virtools Dev contains a suite of algorithms to help programmers create, visualise, manipulate, and track objects in the virtual environment. Besides, the Virtools VR Pack allows users to tailor applications for producing full-immersive, life experiences using the PC-based distributed computing.

The application package for the PC cluster-based CAVE system contains two modules, namely, Product Viewer and Virtual Fabricator, similar to those for the desk-based system.

Fig. 10. Study of a toy design in the CAVE VR environment

The Product Viewer displays a virtual product in a CAVE virtual environment, in which users can fully immerse to manipulate and study the design, as in Figure 10. It also facilitates manipulations of a virtual product, including rotation, and scale up/down, toggling visibility/invisibility of a component, using wireless I/O devices, such as a mouse, a keyboard, and a joystick. The designer can hide the external toy body to study the assembly from different perspectives.

In addition, the Virtual Fabricator, similar to that in the desktop-based system, is created with the Virtools Dev for digital fabrication of multi-material prototypes, as in Figure 11. When the fabrication completes, designers can fully immerse in the CAVE virtual environment for stereoscopic visualisation and quality analysis of the resulting multi-material virtual prototype. This full-immersive environment blocks out most disturbances and hence enhances the efficiency of the design review and improvement process.

It can be seen that the PC cluster-based CAVE system above is relatively convenient and flexible, making full-immersive VR a versatile and affordable tool for small-and-medium sized companies to develop products.

Fig. 11. Digital fabrication of a multi-material toy assembly in a CAVE VR environment

4. Case studies

4.1 A thermometer casing

Figure 12 shows an infrared thermometer commonly fabricated by a manufacturer in Hong Kong. Such products have become very popular as a result of heightened awareness of personal hygiene due to recent outbreaks of infectious diseases. The thermometer is assembled with several components of different materials. Using the MMVP system, multi-toolpaths can be efficiently planned to fabricate a digital prototype of the thermometer casing. Subsequently, the prototype quality can be evaluated by stereoscopic visualisation and superimposition of the prototype on its STL model.

Figure 13 shows the complete multi-material digital prototype, while Figure 14a superimposes it on the STL model for visual analysis. It can be seen that there are excessive materials on the prototype. The overall accuracy of the prototype was evaluated by calculating the average and maximum cusp heights, which are 0.027mm and 0.060mm, respectively. In Figure 14b, green pins and red pins are used to highlight unacceptable deviations exceeding 0.055mm and the maximum deviations, respectively. Therefore, using the MMVP system, the MMLM process may be conveniently iterated with new sets of process parameters without incurring much extra cost. Hence, an optimal combination of process parameters can be obtained for subsequent fabrication of physical prototypes of satisfactory quality.

Fig. 12. A colour STL model of an infrared thermometer casing

Fig. 13. Digital fabrication of the thermometer casing

Fig. 14a. Digital multi-material thermometer casing and superimposition on its STL model

Fig. 14b. Areas of the thermometer casing with dimensional deviation beyond design limits

4.2 A jewellery product – a necklace

Hong Kong is a leading exporter of jewellery products. As such products get more fashion-oriented, innovative designs become more important. Local jewellery manufacturers have realised that they should not only rely on the skills of individual craftsmen. Some have recently adopted LM technology to develop high value-added jewellery items. Hence, the proposed multi-material virtual prototyping system will be particularly useful for building

digital multi-material prototypes to help improve designs and shorten development cycles of jewellery products at competitive costs. Designers can view and evaluate their designs with digital prototypes instead of physical ones, at minimal costs and time possible. Furthermore, digital prototypes may be conveniently transmitted over the Internet to facilitate global manufacturing.

Fig. 15. A multi-material necklace

Figure 15 shows an example of a fashion necklace, and the MMVP system is used to produce digital prototypes of such products. Figure 16 shows the digital fabrication process and the complete multi-material digital prototype, which can be stereoscopically visualised for quality analysis, as in Figure 17a. The necklace prototype can also be superimposed on its STL model to highlight the excessive materials, as shown in Figures 17b and 17c. The average and maximum cusp heights of the prototype, which are 0.260mm and 0.554mm, respectively, are calculated for evaluation of the overall accuracy of the prototype. In Figure

17c, green pins and red pins are used to highlight unacceptable deviations exceeding 0.550mm and the maximum deviations, respectively. Therefore, using the MMVP system, the designers can conveniently perform quality analysis and iterate the MMLM processes. Thus, an optimal combination of process parameters such as, the build direction, layer thickness, and hatch space can be obtained for subsequent fabrication of physical prototypes.

Fig. 16. Digital fabrication process of a multi-material prototype of the necklace

Fig. 17a. Stereoscopic view for visualisation of the necklace prototype

Fig. 17b. Superimposition of the necklace prototype and on its STL model

Fig. 17c. Areas of necklace prototype with dimensional deviations beyond design limits

5. Conclusion

This chapter proposes a VP system which integrates the good features of semi- and full-immersive VR to enhance the versatility and effectiveness of virtual simulation for product design and digital fabrication of multi-material prototypes at affordable cost.

The VP system comprises mainly a suite of software packages for simulation of MMLM processes, including multi-toolpath planning, build-time estimation, and accuracy analysis. It can drive a desktop-based VR system with either a monitor or a large non-depolarising screen to generate a semi-immersive VR environment, which is cost-effective, portable, and easy to operate, for review and improvement of product designs. To minimise disturbances and to enhance the level of immersion, the VP system can control a PC cluster-based CAVE system to create a full-immersive VR environment that enhances collaboration and communication of a design team working on product development. It is indeed an effective and versatile tool for rapid product development to meet ever-increasing diversities of customer demands, stringent cost control, and complexity of new products.

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This book provides an open platform to establish and share knowledge developed by scholars, scientists, and engineers from all over the world, about various applications of the modeling and simulation in the design process of products, in various engineering fields. The book consists of 12 chapters arranged in two sections (3D Modeling and Virtual Prototyping), reflecting the multidimensionality of applications related to modeling and simulation. Some of the most recent modeling and simulation techniques, as well as some of the most accurate and sophisticated software in treating complex systems, are applied. All the original contributions in this book are joined by the basic principle of a successful modeling and simulation process: as complex as necessary, and as simple as possible. The idea is to manipulate the simplifying assumptions in a way that reduces the complexity of the model (in order to make a real-time simulation), but without altering the precision of the results.

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