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Topology Control and Routing in Large Scale WSNs

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1. Introduction

Achieving maximum lifetime in stationary WSNs by optimally using the energy within sensor nodes has been the subject of significant researches in the last recent years. In this field and as already stated, radio transmission and reception operations are being identified as one of the most energy consuming features.

On the other hand, the development of large-scale sensor networks has drawn a lot of attention. Indeed, according to the application, the number of sensor nodes deployed to sense a specific phenomenon may be in the order of hundreds or thousands and can reach a value of millions. Therefore, the large size of wireless sensor networks inevitably introduces significant scalability concerns. One of the main challenges is then to set up new architectures and mechanisms that can efficiently scale up with the growing number of nodes that may be required to ensure adequate coverage of large areas of interest. At the same time, these new architectures and mechanisms should maintain low energy consumption per node so as to get by with energy guaranty acceptable network lifetime. The evaluation of the scalability of an algorithm or protocol is mainly based on a well-known metric for WSNs, which is the network lifetime. The objective is to avoid significant degradations of the network lifetime when the number of nodes composing the WSN increases.

One promising approach to solve the problem of scalability is to build hierarchies among the nodes, such that the topology of the network is abstracted (Chen et al., 2006). Indeed, flat topologies are difficult to scale up since communications between thousands or perhaps millions of nodes in an ad hoc fashion lead to degraded performances and hence higher energy consumption. For instance, the routing algorithm proposed in (Slama et al., 2006), requires that the sink have knowledge of the topology of the entire network at the beginning of each round. This requires a lot of signalling and does not scale well with a high number of nodes.

Hierarchical topologies are then recommended in such scenarios. The network protocols or algorithms designed for these architectures are generally highly scalable. Moreover, such architecture enables better resources allocation and improves power control over the network (Rabiner Heinzelman et al., 2000).

Such architectures are consisted of sensor clusters and one or more base stations. Each cluster is managed by a cluster head. Cluster members are generally small sensor nodes that capture relevant information from the area of interest and send it to their cluster head. This latter creates from the received data a comprehensive local view that is then sent to a base station (or sink). By combining all the data received from the different cluster heads, the base stations generate a comprehensive global view for the entire WSN coverage that it finally sent to the application level. In practice, cluster members do not communicate with each others whereas cluster heads can be involved in inter cluster heads relaying. Both cluster members and cluster heads are battery powered and energy constrained. However, cluster heads are considered to have more computing and storage capacities than member nodes. Base stations can be mobile or located in flexible positions and have infinite processing, storage and power resources. In such scenario, if a sensing node (cluster member) is drained out of energy, the cluster head may still be able to provide a comprehensive local-view by data generated by other sensor nodes in the cluster. However, if a cluster head runs out of energy, the whole cluster coverage is broken. More than that, the relaying task performed by this cluster head from/to neighboring cluster heads toward the sink is also lost. This may affect routes and lead in some cases to the disconnection of an entire region of the network, which may be dramatic for the network mission. Therefore, we are more concerned about the energy constraint of cluster heads.

Although cluster heads can have better initial energy provisioning than sensor nodes, cluster heads also consume energy at a considerably higher rate due to the transmission of gathered data over much longer distances (Pan et al., 2003). Moreover, cluster heads relay not only data generated within their own clusters but also data they may receive from their cluster head neighbors. Cluster heads also consume considerable energy for managing their clusters and gathering information from their cluster members (reception operations, data aggregation, signaling, etc). Cluster heads perform then two high energy cost roles. The first is related to forwarding and relaying tasks and the second concerns their own cluster management. To increase the network lifetime, the communication between the cluster heads should be managed in an energy efficient manner. To this end, an energy aware routing scheme should be investigated to fairly balance the energy consumption among the cluster heads according to both their available amount of energy and their role in the network and then route around cluster heads that are dying or need higher energy to manage their clusters.

On the other hand, base stations have infinite processing, storage and power resources. Therefore, an efficient usage of these flexible and mobile base stations to increase the network lifetime should be investigated especially when the sensing nodes and cluster heads are stationary or have very low mobility. The idea behind this is to decrease the distance between each cluster head and the nearest base station. In fact, when a higher number of base stations are distributed within the WSN, the paths length from any cluster head to its nearest base station is decreased leading to lower energy consumption and therefore to higher network lifetime. Moreover, since multi hop communication is used between cluster heads, the ones that are one hop from the base station drain their energy faster than other nodes because they have to relay messages originated from many other nodes (cluster heads) in addition to delivering their own messages. Therefore, using mobile base stations may help distributing the energy consumption over the different relaying

cluster heads and then increase the network lifetime. Base stations trajectories can be rather controlled by the application or follow a specific mobility model in which case an estimation of their locations can be computed like in (Chen et al., 2006).

Motivated by these issues, we focus, in this chapter, on first, how to optimally locate the base stations in the network and second, on how to arrange the communication between cluster heads toward the base stations, both in order to guaranty that the gathered information effectively and efficiently reach the application. This is generally referred to as *topology control*. Our goal is to maximize the lifetime of a large-scale and energy constrained WSN.

The remainder of this chapter is organised as follows. A related work is presented in section 2. In section 3, we give the system architecture of a two-tiered WSN, its Cluster Heads energy dissipation model, and the definition of the whole network lifetime. In section 4, we present the approach that optimally locates multiple mobile base stations in the network such that the energy consumption is fairly distributed over the different Cluster Heads. In section 5, by extending the optimal routing approach presented in (Slama et al., 2006), we introduce a new optimization scheme that arranges the multi-hop communication between the Cluster Heads while considering their residual amount of energy and the role they play in the network leading to a maximum network lifetime. This new optimal routing scheme takes into account the energy required by each Cluster head to gather data from its cluster as well as to relay the packets coming from its Cluster Head neighbors toward the corresponding base station. We describe then in section 6 the overall dynamic framework. Simulations conducted to evaluate this global approach are described and commented in section 7. Section 8 concludes this chapter and points out the directions for future work.

2. Prior Work

To solve energy constrained problem in wireless sensor networks field, many routing protocols have been proposed; especially, cluster based routing protocols have many advantages such as reducing control messages, maximizing bandwidth reusability, enhanced resource allocation, larger scalability and improved power control.

LEACH (Low-Energy Adaptive Clustering Hierarchy) proposed in (Rabiner Heinzelman et al., 2002) includes a distributed cluster formation technique that enables self-organization of large numbers of nodes and rotating cluster head positions, so that the high energy dissipation in communicating with the base station is spread over all sensor nodes in the sensor network. However, LEACH can suffer from the clustering overhead that may result in supplementary power consumption. Moreover, cluster head rotation requires that all the nodes be capable of performing data aggregation, cluster management and routing decisions. This results in extra hardware complexity in all the nodes.

In contrast, in (Mhatre and al., 2005), the above complexity is embedded in only few nodes (cluster head nodes). In (Mhatre and al., 2005), authors aim to obtain the minimum number of sensing nodes, cluster heads, and battery energy to ensure at least T unit of lifetime. Nodes were divided into two categories: nodes 0 are sensing node and nodes 1 are cluster heads. Analysis results show that the number of cluster heads should be of the order of square root of the number of sensing nodes. However, authors don't give any exact evaluation of the maximum lifetime of the network. Moreover, it was assumed in this work

that cluster heads directly communicate (i.e. one hop communication) with the base station, which is difficult to be applied to realistic scenarios. It has also been observed that the nodes close to the cluster heads have high-energy consumption due to packet relaying operations. But, one of the most significant observation is the sharp cutoff effect, to maximize the lifetime does not hold at all time.

In (Pan et al., 2003), a two-tiered wireless sensing network was considered and the authors observed the property that the first tier nodes are important for the lifetime of the entire network. They investigated a topology control approach to maximize the topological lifetime of the network in terms of the base station placement for the two-tiered sensor networks where the nodes are deployed within clusters. However, the optimal base station locations were obtained without considering the inter-cluster heads relaying. Then, once the base stations located, the inter cluster heads relaying may be not applicable in some cases.

In (Luo & Hubaux, 2005), authors have developed an analytical model that describes the communication load distribution in WSNs and proved that base station mobility is a strategy that deserves to be considered when optimizing the network lifetime. They have further shown that the optimum movement strategy for a mobile base station is to follow the periphery when the deployment area is circular.

Network lifetime elongation using mobile base stations has also been investigated in (Wang et al., 2005). The author gave a novel linear programming formulation for the joint problem of determining the movement of the sink and the sojourn time at different points in the network. Simulations have shown that lifetime maximizing solutions are achieved by non-uniform sojourn time distributions among grid points depending on the shape of the deployment area.

In (Gandham et al., 2003), authors propose to divide time into rounds and to dynamically relocate multiple sinks, at different positions along the periphery of the sensed field, at the beginning of each of these rounds. An integer linear program is used to determine the new locations of the different base stations. Results have shown that the energy consumption of individual sensor nodes is better balanced and the overall energy consumption of all sensors is minimized.

In (Kim et al., 2006), authors propose a different approach to find the optimal locations of multiple stationary sink nodes. The proposed scheme allows sensor nodes to communicate with one or multiple sinks through multiple paths in order to improve the network lifetime.

Another approach to solve the problem of multiple mobile base station placements is proposed in (Vincze et al., 2006). An electrostatic model is applied to determine sinks' locations and to coordinates the movements of these sinks considering the network state.

Unfortunately, most of the above base stations locations strategies are proposed and evaluated over small to medium size wireless sensor networks (typically less than 100 nodes). For large-scale wireless sensor networks, where hundreds or thousands of nodes can be deployed, the placement of multiple base stations still requires advanced studies. For instance, and as illustrated on Fig. 1, if we consider the case where the sinks are located along the periphery as stated in (Gandham et al., 2003), the paths between each node and its nearest sink is relatively short when the number of nodes is limited. However, the more the area size increases and/or the number of nodes within it increases, the longer this path is and the shorter the sensor nodes lifetime will be.

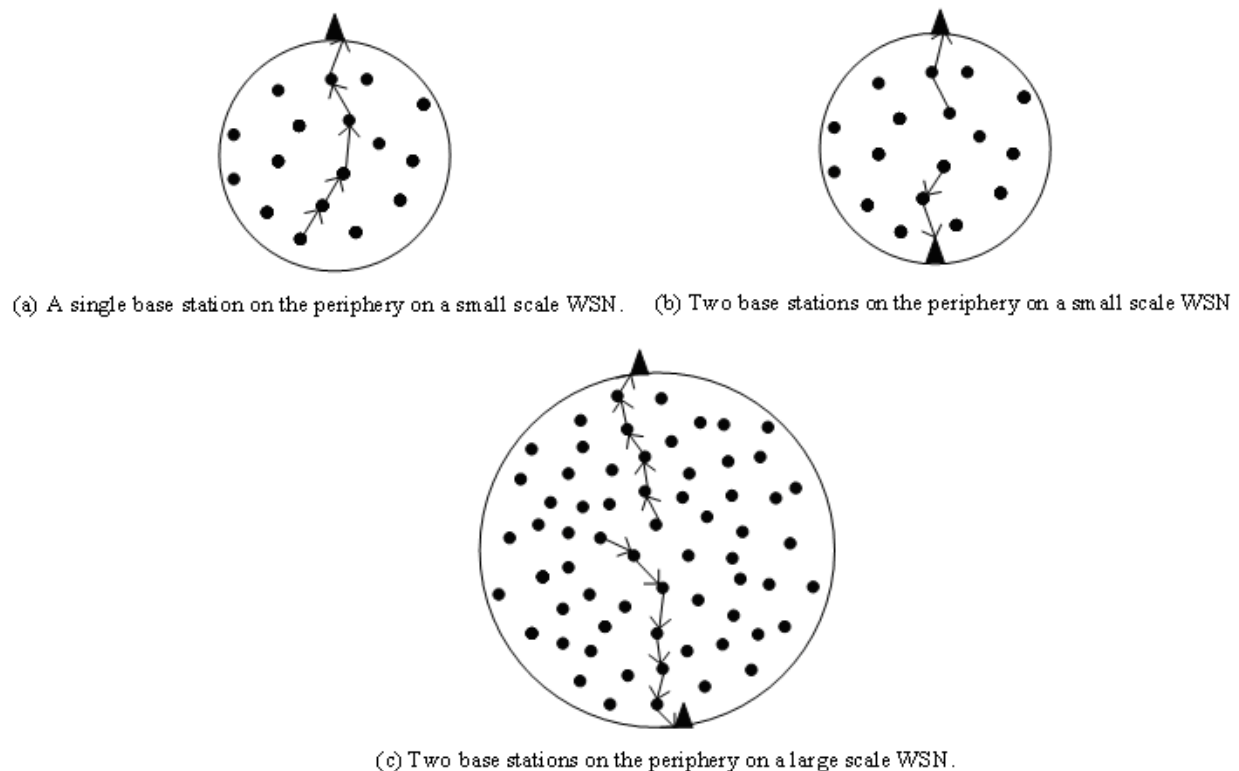


Fig. 1. Multiple Base Stations placement.

3. System Model

3.1 Network architecture

We consider, in this work, a large number of stationary and heterogeneous sensor nodes covering a given area of interest. For scalability management ends, the topology of the network is abstracted and the nodes are organized into a two-tiered WSN as depicted in fig. 2.

It consists of a number of clusters and multiple mobile base stations. Each cluster is composed of a set of Sensing Nodes and one Cluster Head. Sensing Nodes are small, low cost and densely deployed in each cluster. They are responsible of sensing raw data and then forwarding it to their corresponding Cluster Head. We consider that cluster formation is based on neighborhood. Hence, direct transmissions can be used inside each cluster. However, Sensing Nodes do not communicate with other Sensing Nodes in the same or other clusters. Cluster Heads, on the other hand, have much more responsibilities. First, they manage their clusters (send queries, instruct some nodes to be in idle or sleep status...) and gather data from their cluster members. Second, they perform aggregation of this data to eliminate redundancy and minimize the number of transmissions and thus save energy. The aggregated data at each Cluster Head represents a local view of its cluster. Third, they transmit the composite bit-stream towards the nearest base station. Each base station can then generate a comprehensive global view of the entire network coverage by combining the different local view data received from the different Cluster Heads (Pan et al., 2003).

While direct communication is used between Sensing Nodes and Cluster Heads, it may be inappropriate between Cluster Heads and Base Stations. Indeed, distances between them can be large. In such cases, direct transmissions will require high power consumption. In

addition, direct transmissions may be simply impossible since Base Stations can be out of the range of some Cluster Heads. Multi-hop communication is then used. Consequently, Cluster Heads can also be involved in inter Cluster Head relaying.

Two main roles/responsibilities can be then defined for Cluster Heads. The first is related to their clusters and consists of managing their cluster members and gathering information from them. The second is related to forwarding activities and consists of relaying their own packets as well as packets they may receive from their Cluster Head neighbors towards the corresponding Base Station.

Although, both Sensing Nodes and Cluster Heads are energy constrained, Cluster Heads are considered to have more computing and storage capacities than member nodes. Base Stations, however, have infinite processing, storage and power resources. They can be mobile or located in flexible positions.

Note that initial energy allocation plays an important role in topology control for WSNs. Attributing different initial energy levels to the nodes according to their position and role in the network can significantly improve the network lifetime (Pan et al., 2003). However, since fixed initial energy scheme is used in practice (among nodes of the same category, Cluster Heads or Sensing Nodes), we adopt this scheme for the rest of this chapter.

In such scenario, Cluster Heads represent the logical bridge between the two tiers of the network architecture: the lower-tier Sensing Nodes and their Cluster Heads and the upper-tier Cluster Heads and Base Stations. They are then vital for the network mission success. Therefore and as stated previously, Cluster heads should be given all our attention in terms of energy efficiency.

Once Cluster Heads and Sensing Nodes are deployed, an immediate challenge is to optimally locate the Base Stations such that the network lifetime is maximized. After Base Stations are located, these latter can compute the inter-Cluster Heads routing scheme. This scheme should instruct Cluster Heads to communicate in an energy efficient manner and fairly distribute the energy consumption among them to achieve a longer network lifetime.

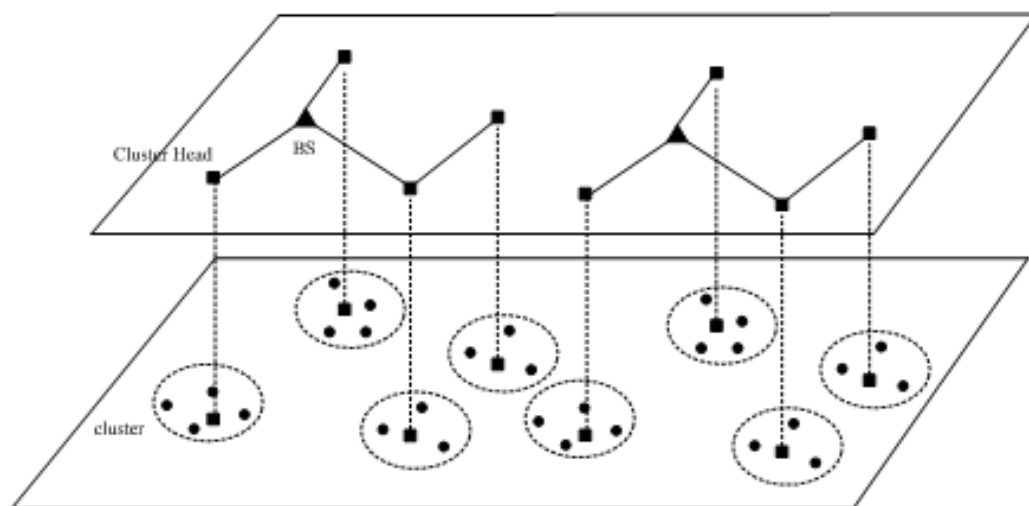


Fig. 2. A two-tiered Wireless Sensor Network.

3.2 Network Graph

We consider that the network is organized into N Clusters with one Cluster Head for each Cluster. In the rest of this chapter, we will note a Cluster i by C_i and its corresponding Cluster Head by CH_i , $i=1$ to N . All the Sensing Nodes in cluster C_i can communicate directly with the Cluster Head CH_i .

The network is modelled as an undirected connected graph $G(H,A)$ where H is the set of Cluster Heads, $H = \{CH_i, i=1 \text{ to } N\}$ and A the set of all undirected links (CH_i, CH_j) where CH_i, CH_j are two Cluster Heads of H .

Let L_i be the set of Cluster Heads neighbors of Cluster Head CH_i . L_i is composed of all Cluster Heads that can be reached by CH_i using a transmission power equal or less than a maximum predefined threshold. All links are assumed to be bidirectional.

3.3 Energy Model

In this work, we assume the same radio energy model used in (Slama et al., 2006). We remind that E_{elec} and ε_{amp} represent the energy consumed respectively to run the radio electronics and the power amplifier.

Thus, the energy consumed at node i when transmitting information to node j at rate x_{ij} can be written as:

$$E_t(x_{ij}, d_{ij}) = (E_{elec} + \varepsilon_{amp} \cdot d_{ij}^2) x_{ij} = e_{ij} \cdot x_{ij} \quad (1)$$

And the energy consumed at node j when receiving information from node i at rate x_{ij} :

$$E_r(x_{ij}) = E_{elec} \cdot x_{ij} = e_r \cdot x_{ij} \quad (2)$$

Moreover, since data aggregation (fusion) is performed within the network, the energy consumed at node j to aggregate information received from node i at rate x_{ij} can be written as :

$$E_a(x_{ij}) = \gamma \cdot x_{ij} = e_a \cdot x_{ij} \quad (3)$$

Where:

d_{ij} is the Euclid distance between node i and node j .

e_{ij} is the transmission energy required to transmit one data unit from node i to node j .

e_r is the energy required for the reception of one data unit.

γ is constant and called the aggregation energy consumption coefficient (Chen et al., 2006).

e_a is the energy required to the fusion of one data unit.

3.4 Lifetime Definitions

First, we consider that each cluster in the network dies when no more reliable information can be delivered from the cluster members. A Cluster Head whose cluster is dead, continue performing relaying data from/to neighboring Cluster Heads (i.e., its second role).

Second, we define the lifetime of the whole network as the metric for determining the optimality of the routing algorithm.

In a previous work (Slama et al., 2006), we defined the lifetime of a flat topological small-scale sensor network as the time at which a first node runs out of energy. Analogically and motivated by the same reasons, we define in this work the lifetime of the whole cluster-based sensor network as the period of time that ends when a first Cluster Head runs out of energy. This implies that every Cluster Head is vital for the application and cannot be substituted by others.

Hence, maximizing the network lifetime can be achieved by delaying as much as possible the first Cluster Head death.

4. Base stations placement

We propose in this section to enhance Base Station placement in a two-tiered large-scale WSN.

The idea behind this is to efficiently deploy Multiple Mobile Base Stations within the network. Multiple Base Stations are used to decrease the distance between each Cluster Head and its nearest Base Station. Base Stations are also chosen to be mobile to make the set of Cluster Heads close to the Base Stations and then overloaded, change over the time. This should guaranty a fair distribution of the energy consumption among the different Cluster Heads in the network and hence improve the network lifetime. The Challenge here is then to define the initial locations and the movement trajectories of the different Base Stations.

Since we deal with a large-scale WSN, an intuitively appropriate solution is to decompose the underlying sensor network and then optimize energy usage in each of the sub-networks independently. The objective is to take advantage of the powerful and efficient Base Station placement techniques proposed for small scale WSNs. In order to apply these techniques over large-scale WSNs, we propose to first divide the network into sub-networks according to specific criteria. An adequate Base Station placement technique can then be applied independently within each of the defined sub-networks.

Graph partitioning is a promising approach to split a large sensor network into balanced sub-networks. In practice, different criteria can be considered in order to partition a large-scale two-tiered wireless sensor network. Since multi-hop communication is used between Cluster Heads toward Base Stations, one simple objective is to create balanced sub-networks (in terms of number of Cluster Heads/clusters) that group the Cluster Heads according to their neighborhood. This allows creating smaller two-tiered sub-networks with similar characteristics that can be easily optimized, independently but in the same way.

In graph theory related literature, different approaches and techniques are proposed for balanced graph partitioning.

4.1 Existing Graph Partitioning Techniques

In (Even et al., 1997), a fast approximate graph-partitioning algorithm is proposed. The authors unified the problems of *b-balanced* cuts and *k-multiway* separators using a new approach called minimum capacity ρ -separators. They studied the graph partitioning problems on graphs with edge capacities and vertex weights and described a simple approximation algorithm for minimum capacity ρ -separators leading to a fast approximation algorithm both for *b-balanced* cuts and *k-multiway* separators. They define a ρ -separator as a

sub-set of edges whose removal partitions the vertex set into connected components such that the sum of the vertex weights in each component is at most ρ times the weight of the graph.

In (Ito et al., 2006), authors considered three problems to find a (l, u) -partition of a given graph. They proposed to partition a graph G into connected components by deleting some edges from G making the total weight of each component equal at least to l and at most to u . The minimum partition problem is to find an (l, u) -partition with the minimum number of components, the maximum partition problem is defined in the same way and the p -partition problem is to find an (l, u) -partition with a fixed number p of components. Authors proved that the three problems are *NP-complete* or *NP-hard*.

In (Chlebikova, 1996), authors studied the approximation of the Maximally Balanced Connected Partition problem (MBCP). They first presented the optimization problem that finds the maximally balanced connected partition for a graph G . It results in a partition (V_1, V_2) of V composed of disjoint sets V_1 and V_2 such that both sub-graphs of G induced by V_1 and V_2 are connected, and maximize an objective function "balance", $B^w(V_1, V_2) = \min(w(V_1), w(V_2))$. Authors proved that the problem is *NP-hard*.

In this work, this last approach will be adapted and applied to our Network. Our choice is mainly motivated by the practical approach provided in (Chlebikova, 1996) and based on the use of a polynomial-time algorithm that gives an approximate solution.

In the following the Maximally Balanced Connected Partition (MBCP) technique (Chlebikova, 1996) is adapted and formulated. A corresponding approximate resolution algorithm is then presented.

4.2 Problem formulation

Since, in Base Stations placement scheme, we are considering the communication between the Cluster Heads and the Base Stations (the upper tier of the architecture), only Cluster Heads are concerned by the partitioning scheme. We assume then that if a Cluster Head belongs to a sub-network, then its corresponding Cluster belongs to this sub-network as well.

We consider here the undirected connected graph $G(H, A)$. We remind that H is the set of Cluster Heads, $H = \{CH_i, i = 1 \text{ to } N\}$ and A the set of all undirected links.

The objective is to partition G into connected balanced sub-graphs.

To achieve this objective, let w be a non-negative vertex-weight function representing the balancing criteria. In this case, w will reflect the number of Cluster Heads. Hence $w(H') = |H'|$.

This MBCP problem can then be formulated as follow:

$$\text{Maximize } B^w(H_1, H_2) = \min(w(H_1), w(H_2))$$

Subject to 1. (H_1, H_2) is a partition of H into non-empty disjoint sets H_1 and H_2 such that sub-graphs of G induced by H_1 and H_2 are connected.

$$2. w(H') = \sum_{CH_i \in H'} w(CH_i) \quad \forall H' \subseteq H$$

The resolution of this model will result into two balanced sub-networks. Each of them can be partitioned again using the same process.

This partitioning technique should be applied as much as required according to the targeted size for the sub-networks and taking into account the number of available Base Stations to be placed. The final result should be 2^n equivalent smaller connected sub-networks where n is the number of partitioning iterations.

4.3 Problem resolution

To solve this model, we used the polynomial approximation algorithm presented in (Chlebikova, 1996) and which finds an approximate solution for the MBCP problem.

In order to select neighbouring Cluster Heads within the same sub-networks, we adapted this algorithm by sorting the list of candidates for each partition according to their distance (vicinity). Fig. 3 illustrates an example of a WSN partitioned into four sub-networks.

The algorithm can be written as follow:

Input: $G = (H, A)$.

$H = \{CH_1, CH_2, CH_3 \dots CH_N\}$ where $N = |H|$.

0. Initialize $H_1 = \{CH_1\}$, $H_2 = H \setminus H_1$ such as CH_1 a Cluster Head near the periphery of the network.

1. If $|H_1| \geq 1/2 |H|$ then Step 3 else Step 2.

2. Let $H_0 = \{CH_i \in H / (H_1 \cup \{CH_i\}, H_2 \setminus \{CH_i\}, i \in \{1..N\}) \text{ is a connected partition of } G\}$.

Choose CH_i of H_0 such that CH_i the closest element to H_1 .

If $|CH_i| < |H| - 2|H_1|$

 then $H_1 := H_1 \cup \{CH_i\}$, $H_2 := H_2 \setminus \{CH_i\}$, Step 1

 else Step 3

3. Return (H_1, H_2) .

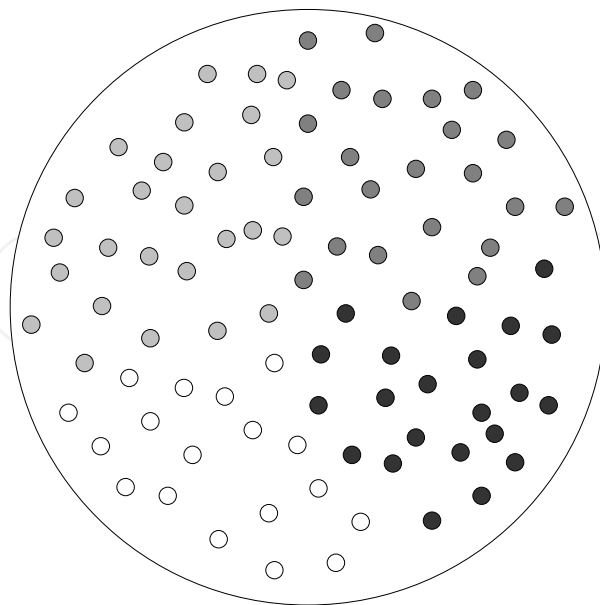


Fig. 3. A Wireless Sensor Network partitioned into 4 sub-networks (the four node patterns represent four different sub-networks).

4.4 Locating Base Stations

Once the network is partitioned into identical smaller two-tiered sub-networks, each of these sub-networks is represented by a disc with the geographic centre of the sub-network as centre and the distance between this centre and the farthest Cluster Head (belonging to this sub-network) from it as radius. Recall that if a Cluster Head belongs to a sub-network, then its Cluster members belong to this sub-network as well.

Base Stations can now be optimally located within each of these sub-networks independently but in the same way.

It has been proven in (Luo & Hubaux, 2005) that the optimum movement for a mobile base station is to follow the periphery when the deployment area is circular.

Motivated by this result, we suggest in this work that one single Base Station be randomly deployed on the periphery of each sub-network. Then each Base Station keeps moving along the periphery of the sub-network in which it was deployed. Note that Cluster Heads can send their data only to the Base Station deployed in the sub-network they belong to.

A mobile base station can move in two different regimes, a fast mobility regime and a slow mobility regime (Luo et al., 2006). In the fast mobility regime, the base station moves in a continuous form with a velocity v along the time without any stop or pause in a particular position. In the slow mobility regime, the base station moves in a discrete form and its trajectory is a sequence of anchor points between which the base station moves with a velocity v and at which it pauses during a period of time (epoch).

The slow mobility regime is considered more realistic and is adopted in many research studies. Therefore, we assume in this work that each Base Station moves in a slow mobility regime. We propose then to divide time into rounds. Each Base Station moves then at the beginning of each round and remains at its new position until the end of the round.

It is very important to carefully choose the value of the base station velocity. In fact, when the mobile base station velocity is high, the base station will more frequently change its position and visit more the different regions over the area of interest during the network lifetime. Therefore, the energy consumption is efficiently distributed over the cluster heads and the network lifetime is extended. This can be much more efficient in the particular case where the cluster heads buffer the data gathered in their clusters and wait until the base station approaches to deliver it (Chen et al., 2006) which reduces unnecessarily packet forwarding actions since cluster heads are sure of base station arrival before losing the data (because of buffer size limitation or packet deadline expiration). Besides, the high speed moving base station produces a tolerable data delivery delay especially in the case of fast mobility regime, which can be very important for some specific applications. However, base station high velocity can have negative effects. In fact, it can make the session interval too short to successfully exchange a long data packet and hence the packet loss rate will increase. In slow mobility regime, it is preferred that the epoch (round) be long enough to guaranty long messages exchange.

On the other hand, it seems obvious that the mobility of the base stations will inevitably incur additional overhead in data exchanges since the cluster heads will continuously need to be informed of their corresponding base station location. However, it has been proved in (Luo et al., 2006) that when using a slow mobility regime with an epoch much longer than the base station moving time, the overhead introduced by the mobility of the base station

became negligible because amortized across a long epoch. This reinforces our choice in using a slow mobility regime.

After determining the Base Stations placement strategy, we can further prolong network lifetime by instructing Cluster heads to efficiently forward the data to the destination. Hence, at the beginning of each round and after it is located in its new position, each Base Station has to compute the routing scheme that will manage in an energy efficient manner the inter Cluster Heads communication within its corresponding sub-network.

5. Inter-Cluster Head communication

As discussed at the beginning of this chapter, Cluster Heads that are in critical positions run out of energy first. Hence, to further extend the network lifetime, it is necessary to delay as much as possible the first Cluster Heads death.

For small-scale non-clustered WSNs, we proposed in a previous work (Slama et al., 2006) an approach that defines an optimal multi-hop routing. It dynamically distributes flows proportionally to the residual energy available at each node leading to a maximum network lifetime.

The routing scheme is modelled as an optimization algorithm and is computed at the Base Station. Its resolution results in a routing matrix that defines for each node to which of its neighbors it has to send data.

In this section, we propose to extend this approach to two-tiered WSN architectures. In addition to the residual energy at each Cluster Heads, we introduce a new constraint that reflects Cluster Head energy consumption related to its intra-cluster activities (i.e. the first role of Cluster Heads). The idea is to alleviate, from relaying activities (i.e. the second role of Cluster Heads), Cluster Heads requiring higher energy for managing their clusters.

On the other hand, inside each cluster, Sensing Nodes have to provide the information required by the end application. They should be organized such that the QoS is satisfied with minimum cost. Different techniques can be used to achieve this goal. For instance, sensors can be autonomous and self organized (Rabiner, Heizelman et al., 2002, Chatterjee et al., 2002). Another approach is to use a relative central mechanism (e.g. scheduling mechanism) that can take the appropriate decisions on behalf of the Sensing Nodes. For instance, we can consider that within each cluster, one or more Sensing Nodes may be used at any time to provide data to the application, but only certain subsets of available sensors may satisfy channel bandwidth and/or application quality of service constraints (Perillo & Heizelman, 2003). In this work, we decide to adapt the scheduling mechanism, initially proposed in (Perillo & Heizelman, 2003) for a flat topological WSNs, to manage communications inside the clusters. This scheduler determines which sensor sets should be used and for how long time so that the lifetime of the cluster is maximized while the necessary quality of service expected from this cluster is always maintained at the application. In addition, Sensing Nodes providing redundant information can be turned off which contributes in energy saving and reduces data flows. Used within each cluster and according to the performance evaluation given in (Perillo & Heizelman, 2003), this mechanism optimizes individual clusters lifetimes.

In order to achieve a global routing optimization, the inter-Cluster Heads communication approach that we propose should, in addition, take into account these individual clusters lifetimes, as the more a cluster lasts, the more its Cluster Heads requires energy for its management (e.g. reception, data processing and fusion, ...).

This inter-Cluster Heads communication approach is modeled within each sub-network as an optimization problem. It is then processed in a centralized manner at the Base Station of each sub-network independently but simultaneously. It takes into account the current status and topology of the sub-network and results in a routing matrix that defines the inter-Cluster Heads flows within this sub-network such that the minimum Cluster Head lifetime is optimized.

The inter-Cluster Heads communication approach construction and its details are presented in the following sections.

5.1 Model and Notations

Let's consider N_b Base Stations to be deployed in the network. We note a Base Station k by b_k , $k = 1$ to N_b . The network graph G is then partitioned into N_b equivalent sub-graphs. We consider $(H_1, H_2, \dots, H_{N_b})$ the connected partition of G .

Then, each sub-network k corresponding to H_k contains one single mobile Base Station b_k and N_k^{CH} Cluster Heads, $k = 1$ to N_b , $\sum_k N_k^{CH} = N$.

We assume that each sub-network k is modeled as a connected sub-graph $G_k(H_k, A_k)$, $k = 1$ to N_b . H_k is then the set of Cluster Heads belonging to the sub-network k , $H_k = \{CH_{k,i}, i = 1$ to $N_k^{CH}\}$ and A_k the set of the undirected links $(CH_{k,i}, CH_{k,j})$ where $CH_{k,i}$ and $CH_{k,j}$ are two Cluster Heads of H_k .

Let $L_{k,i}$ be the set of Cluster Heads neighbors of Cluster Head $CH_{k,i}$ in the sub-network k . $L_{k,i}$ is composed of all Cluster Heads of H_k that can be reached by $CH_{k,i}$. All links are assumed to be bidirectional.

We remind that if a Cluster Head belongs to a sub-network than its corresponding Cluster belongs to this sub-network as well. We will note by $C_{k,i}$ the Cluster of Sensing Nodes corresponding to the Cluster Head $CH_{k,i}$ and then belonging to sub-network k , $i = 1$ to N_k^{CH} and $k = 1$ to N_b .

Each cluster $C_{k,i}$ contains $N_{k,i}^S$ Sensing Nodes. We will refer to the complete set of Sensing Nodes within a cluster $C_{k,i}$ as $S_{k,i} = \{S_{k,il}, l \in \{1 \dots N_{k,i}^S\}\}$.

We remind that all Sensing Nodes in Cluster $C_{k,i}$ can communicate directly with their Cluster Head $CH_{k,i}$ and that all Cluster Heads $CH_{k,i}$ belonging to sub-network k have to forward the gathered data to the Base Station b_k deployed within this same sub-network. Also, Cluster Heads belonging to one sub-network cannot communicate with Cluster Heads belonging to another sub-network.

We finally assume that $E_{k,il}^S$ and $E_{k,i}^{CH}$ are the initial energies of Sensing Node $S_{k,il}$ and Cluster Head $CH_{k,i}$ respectively. In table 1, we list all symbols used in this chapter.

5.2 Flow Conservation

We denote by $r_{k,i}$ the arrival rate of information at $CH_{k,i}$ sensed by the Sensing Nodes within its cluster $C_{k,i}$ and we denote by $v_{k,i}$ the rate of information at $CH_{k,i}$ after aggregation.

Hence, $v_{k,i}$ can be written as, $v_{k,i} = f_a(r_{k,i})$. f_a is a typical linear aggregation function such that $f_a(x) = \beta x$ for some constant β , $0 < \beta < 1$. β is called the data aggregation ratio (Chen et al., 2006).

Let $w_{k,i}$ be the average rate of information that transit through $CH_{k,i}$. It is composed of the generated information rate at $CH_{k,i}$ (sensed by the cluster members and then aggregated at $CH_{k,i}$) plus the information rate received from its Cluster Heads neighbours of $L_{k,i}$.

$w_{k,i}$ is given by:

$$w_{k,i} = v_{k,i} + \sum_{j/CH_{k,j} \in L_{k,i}} p_{k,ji} w_{k,j} \quad \forall (k, i \in \{1 \dots N_k^{CH}\}) \quad (4)$$

and

$$w_{b_k} = \sum_{i \in \{1 \dots N_k^{CH}\}} v_{k,i} \quad (5)$$

Where $p_{k,ji} w_{k,j}$ is the proportion of data transmitted by $CH_{k,j}$ to $CH_{k,i}$.

Obviously, $p_{k,ij} \geq 0 \quad \forall (k, i, j)$ and $\sum_{j/CH_{k,j} \in L_{k,i}} p_{k,ij} = 1 \quad \forall (k, i \in \{1 \dots N_k^{CH}\})$.

We denote by P_k the routing matrix within sub-network k and which can be written as:

$$P_k = \{p_{k,ij}\}$$

Note that Equations (4) and (5) verify the flow conservation condition. The flow conservation condition states that the sum of information generation rate and the total incoming flow must equal the total outgoing flow.

5.3 Lifetime Model

We remind that a cluster dies when no more reliable information can be delivered from the cluster Sensing Nodes. We denote the lifetime of a cluster $C_{k,i}$ by $T_{k,i}^C$. Once its cluster dead, each Cluster head continue performing relaying activities until it is over of energy. We then denote by $T_{k,i}^{CH}$, the lifetime of Cluster Head $CH_{k,i}$.

The lifetime of the whole network is defined, as stated in section 4.2.4, as the period of time that ends when a first Cluster Head runs out of energy. We analogically define the lifetime of a sub-network k as the period of time until which the first Cluster Head $CH_{k,i}$ dies and denote it by T_k . Then, T_k can be written as:

$$T_k = \min_{i \in \{1 \dots N_k^{CH}\}} T_{k,i}^{CH}, \forall k \quad (6)$$

Thus, the network lifetime can be defined as the period of time until which the first sub-network dies.

The network lifetime, denoted by T_{net} , can then be written as follow :

$$T_{net} = \min_k T_k = \min_{k,i \in \{1 \dots N_k^{CH}\}} T_{k,i}^{CH} \tag{7}$$

Hence, maximizing the network lifetime can be achieved by maximizing each sub-network lifetime simultaneously.

5.4 Intra-cluster Communication

As already mentioned, the intra-cluster communication scheme is inspired from (Perillo & Heinzelman, 2003). The communications inside the clusters is managed by an optimized scheduler that determines which sensor sets should be used and for how long time so that the lifetime of the cluster is maximized while the necessary quality of service is respected. As defined in (Perillo & Heinzelman, 2003), a sensor set is determined to be *feasible* if i) the total bandwidth necessary to support the set is below the capacity of the cluster and the traffic is schedulable and ii) the set provides the necessary reliability to the application. We will refer to the set of feasible sensor sets in a cluster $C_{k,i}$ as $F_{k,i} = \{F_{k,im}, m \in \{1 \dots N_{k,i}^F\}\}$.

Symbol	Description
N	the number of Cluster Heads/Clusters in the network.
H	the set of N Cluster Heads of the WSN.
A	the set of the undirected links between the Cluster Heads of H
CH_i	a Cluster Head of H .
C_i	the Cluster corresponding to CH_i .
L_i	the set of Cluster Heads neighbours of CH_i .
N_b	the number of base stations deployed in the network.
H_k	a partition of H .
b_k	the base station deployed in sub-graph k .
$CH_{k,i}$	a Cluster Head of H_k .
N_k^{CH}	the number of Cluster Heads in sub-graph k .
$L_{k,i}$	the set of Cluster Heads Neighbors of $CH_{k,i}$ in sub-graph k .
$C_{k,i}$	the cluster in sub-network k corresponding to $CH_{k,i}$.
$N_{k,i}^S$	the number of Sensing nodes in $C_{k,i}$.
$S_{k,i}$	the set of Sensing Nodes in $C_{k,i}$.
$S_{k,il}$	a Sensing Node of $S_{k,i}$.
$E_{k,il}^S$	the initial energy of $S_{k,il}$.

$E_{k,i}^{CH}$	the initial energy of $CH_{k,i}$.
$r_{k,i}$	the arrival rate of sensed data at $CH_{k,i}$.
$v_{k,i}$	the arrival rate of aggregated data at $CH_{k,i}$.
β	the data aggregation ratio.
f_a	the aggregation function.
$w_{k,i}$	the average rate of data that transit through $CH_{k,i}$.
w_{b_k}	the average rate of data that transit through b_k .
$p_{k,ij}$	The flow portion transmitted from $CH_{k,i}$ to $CH_{k,j}$.
P_k	the routing matrix within sub-network k .
$T_{k,i}^C$	the lifetime duration of $C_{k,i}$.
$T_{k,i}^{CH}$	the lifetime duration of $CH_{k,i}$.
T_k	the lifetime duration of sub-network k .
T_{net}	the lifetime duration of the whole network.
$F_{k,i}$	the set of feasible sensor sets in $C_{k,i}$.
$F_{k,im}$	a feasible sensor set of $F_{k,i}$.
$N_{k,i}^F$	the number of feasible sensor sets in $C_{k,i}$.
$T_{k,im}^F$	the length of time that $F_{k,im}$ is being used in the optimal Schedule of $C_{k,i}$.
$q_{k,il}$	the power consumption at sensor $S_{k,il}$.
E_{elec}	the energy consumed to run the radio electronics.
\mathcal{E}_{amp}	the energy consumed to run the power amplifier.
$e_{k,ij}$	the transmission energy required to transmit one data unit from $CH_{k,i}$ to $CH_{k,j}$.
e_r	the energy required for the reception of one data unit.
e_a	the energy required to the fusion of one data unit.
γ	the aggregation energy consumption coefficient.

Table 1. Notations

The optimal scheduler that maximizes the lifetime of $C_{k,i}$ determines the length of time that each sensor set in $C_{k,i}$ should be used. Let $T_{k,im}^F$ represent the length of time that feasible sensor set $F_{k,im}$ is being used in the optimal schedule of $C_{k,i}$. The objective of the problem is to maximize the lifetime of each cluster $C_{k,i}$:

$$T_{k,i}^C = \sum_m T_{k,im}^F \quad \forall (k, i \in \{1 \dots N_k^{CH}\}) \quad (8)$$

We will define $a_{k,ilm}$ as a variable equal to one if sensor $S_{k,il}$ is being used in feasible sensor set $F_{k,im}$ of the cluster $C_{k,i}$ and equal to zero otherwise.

Finally, we define $q_{k,il}$ as a variable that represents the power consumption (sensing and communication) at sensor $S_{k,il}$.

We remind that $E_{k,il}^S$ is the initial energy of Sensor Node $S_{k,il}$. This finite energy introduces the following constraint:

$$\sum_m a_{k,ilm} T_{k,im}^F q_{k,il} \leq E_{k,il}^S \quad \forall (k, i \in \{1 \dots N_k^{CH}\}, l \in \{1 \dots N_{k,i}^S\}) \quad (9)$$

This scheduling problem has been modeled as a generalized maximum flow graph problem. The same method will be used for each cluster in the network and carried out in a centralized manner by an unconstrained node or at the application level at the beginning of the network deployment and once the clusters are formed (during the set-up phase and before the transmission phase is started). The computation of this optimization scheme defines for each cluster the optimal Schedule that maximizes its lifetime. Each Cluster lifetime value can then be computed and used as an input parameter for the inter-Cluster Heads communication scheme.

To have details about the resolution of this optimization problem the reader is referred to (Perillo & Heinzelman, 2003).

5.5 Maximizing Network Lifetime

According to the scheduling problem described in the last section the lifetime of each cluster $C_{k,i}$ (not including the corresponding $CH_{k,i}$) is $T_{k,i}^C$. During this period of time a Cluster Head $CH_{k,i}$ is providing two functionalities: the first concerns internal exchange (receiving and aggregating data coming from its cluster members) and the second concerns external exchange (receiving, transmitting and relaying the data coming from its Cluster Head neighbors).

Once this period achieved, $CH_{k,i}$, if not yet drained out of energy, expend its remaining energy to provide only the second functionality.

During the period of time $T_{k,i}^C$, $CH_{k,i}$ expends an amount of energy given by:

$$E_{k,i}^{CH_1} = T_{k,i}^C \left(\sum_{j | CH_{k,j} \in L_{k,i}} e_{k,ij} p_{k,ij} w_{k,i} + \sum_{j | CH_{k,j} \in L_{k,i}} e_r p_{k,ji} w_{k,j} + (e_a + e_r) r_{k,i} \right) \quad (10)$$

Here, $e_{k,ij}$ is the transmission energy required to transmit one data unit from $CH_{k,i}$ to $CH_{k,j}$ relatively to equation (1).

So, the remaining energy at $CH_{k,i}$ when $T_{k,i}^C$ is spent is:

$$E_{k,i}^{CH_2} = E_{k,i}^{CH} - E_{k,i}^{CH_1} \quad (11)$$

Hence, according to the energy model described in section 4.2.3, the lifetime of $CH_{k,i}$ under a given system $P_k = \{p_{k,ij}\} \forall (k,i \in \{1 \dots N_k^{CH}\})$ is given by:

$$T_{k,i}^{CH}(P_k) = T_{k,i}^C + \frac{E_{k,i}^{CH_2}}{\sum_{j/CH_{k,j} \in L_{k,i}} e_{k,ij} p_{k,ij} w_{k,i} + \sum_{j/CH_{k,j} \in L_{k,i}} e_r p_{k,ji} w_{k,j}} \\ = T_{k,i}^C + \frac{E_{k,i}^{CH} - T_{k,i}^C (\sum_{j/CH_{k,j} \in L_{k,i}} e_{k,ij} p_{k,ij} w_{k,i} + \sum_{j/CH_{k,j} \in L_{k,i}} e_r p_{k,ji} w_{k,j} + (e_a + e_r) r_{k,i})}{\sum_{j/CH_{k,j} \in L_{k,i}} e_{k,ij} p_{k,ij} w_{k,i} + \sum_{j/CH_{k,j} \in L_{k,i}} e_r p_{k,ji} w_{k,j}} \quad (12)$$

Then, T_k , the lifetime of sub-graph k , can be approximated as follow:

$$T_k(P_k) = \min_{i \in \{1 \dots N_k^{CH}\}} T_{k,i}^{CH}(P_k), \forall k \quad (13)$$

Maximizing the lifetime of a sub-network k can be reached by solving the following optimization problem:

$$\begin{aligned} & \text{Maximize} && T_k \\ & \text{Subject to} && p_{k,ij} \geq 0 \quad \forall i \in \{1 \dots N_k^{CH}\} \text{ and } \forall j/CH_{k,j} \in L_{k,i} \\ & && \sum_{j/CH_{k,j} \in L_{k,i}} p_{k,ij} = 0 \quad \forall i \in \{1 \dots N_k^{CH}\} \\ & && E_{k,i}^{CH_1} + E_{k,i}^{CH_2} \leq E_{k,i}^{CH} \quad \forall i \in \{1 \dots N_k^{CH}\} \end{aligned} \quad (14)$$

The last constraint models energy conservation at each Cluster Head $CH_{k,i}$.

The resolution of this system requires determining the matrix P_k defining, for a fixed position of Base Station b_k , the optimal routing flows that are used by each Cluster Head within sub-network k to forward data to its Neighbors such that the lifetime of this sub-network is maximized. The optimal matrix P_k can then be computed in a centralized fashion at the Base Station b_k .

This optimisation problem is Non Polynomial and can then be solved over Matlab using specific heuristics similar to those used to solve the optimization problem presented in (Slama et al., 2006). Once the different sub-networks lifetimes $T_k, \forall k = 1 \text{ to } N_b$ are computed, the whole network lifetime can be finally given by:

$$T_{net} = \min_k T_k \quad (15)$$

6. Global Framework

In this section we describe the overall dynamic framework for large two-tiered wireless sensor networks lifetime maximization. The framework is based on the optimisation scheme related to both Base Stations positioning and inter-Cluster Head communication presented previously. A cyclic algorithm is then defined to permit the dynamic adaptation of the optimization process (see Fig. 4).

Once the nodes are deployed in the interested area, the network topology is first abstracted and the overall network is partitioned into equivalent sub-networks that have the same characteristics and where the energy consumption can be optimized independently but in the same way. One mobile base station is then randomly deployed on the periphery of each sub-network. Time is then divided into equal periods of time called rounds or epochs. At the beginning of each round, each base station moves along the periphery of its corresponding sub-network. Once it reached its new position, the base station collects information about the current topology status of its sub-network. These information may include The residual energy at each sensor node, the neighbors list and the positions of each node, sources' throughputs, etc.

In a next step, each base station runs the routing optimization process corresponding to its sub-network as described in the previous section and which results in an updated routing matrix that optimally distributes energy consumption over the different Cluster Heads according to their roles in the sub-network and to the residual amount energy at each of them. Data gathering is then performed by the sensing nodes and the collected data is aggregated and forwarded by the cluster heads toward the corresponding base station using the optimized routing probabilities.

Input: $G(H, A)$.

0.1. *The network is divided into N_b equivalent sub-networks.*

0.2. *One mobile base station is deployed on the periphery of each of these sub-networks.*

0.3. *Initial round duration (epoch) is determined at the application level*

While *(the sensor network is operational for the application)* **do**

//begin of the round

$\forall k \in \{1 \dots N_b\}$:

 1. *Base station b_k in sub-network k moves to its new position on the periphery*

 2. *At base station b_k : Collection of all relevant information from all the cluster heads of H_k concerning the current topology of sub-network k .*

 3. *At base station b_k : Run of the optimization process and compute the routing matrix $[P_k]$.*

 4. *Base station b_k transmits to each Cluster Head $CH_{k,i}$ the vector $[P_{k,ij}]$*

$(\forall i \in \{1 \dots N_k^{CH}\} \text{ and } \forall j / CH_{k,j} \in L_{k,i}).$

 5. *Each Cluster Head sends the captured/received information to its neighbors toward b_k according to $[P_k]$.*

// end of the round}

Fig. 4. Global Framework.

7. Simulations

This section is dedicated to the evaluation of the performances of first, the Base Stations Placement scheme that optimally locates the different base stations in the network while considering scalability as well as energy efficiency issues and second, the inter-ClusterHead communication approach formulated as an optimization problem that aims to efficiently and fairly distribute the energy among Cluster Heads while taking into account their roles in the network.

7.1 Base Stations placement

The effect of the proposed partitioning technique on the WSN lifetime is investigated using numerical simulations over Matlab environment. A circular large-scale wireless sensor network, with a radius $R = 500\text{m}$ is considered. In order to study the performance of the base stations placement scheme, we focused on the upper tier of the network architecture (Base Stations and Cluster Heads) independently of the lower tier (Cluster Heads and Sensing Nodes). 1000 nodes (Cluster Heads) are randomly (uniformly) deployed over a network area. All nodes are similar with a communication range $r = 80\text{m}$ and an initial energy of 1000J unit. Base Stations are assumed to have no energy constraints because they have larger batteries or their batteries are rechargeable. We assumed, in this scenario, that the shortest path routing algorithm is used to establish routes from Cluster Heads to base stations. The network lifetime is defined as the moment at which the first node runs out of energy. Time is divided into rounds. Each round is composed of $T = 100$ timeframes. Each sensor node generates one data packet every timeframe.

To evaluate the efficiency of the proposed graph partitioning technique in elongating the network lifetime, three comparative scenarios are considered:

1. Scenario 1:

Case 1: An entire large network (not partitioned) is considered. All the sensors have the same capacity. N base stations are randomly fixed inside the coverage area of interest. Each sensor has to send the data it senses to the nearest base station.

Case 2: The graph-partitioning algorithm (detailed in section 4.3.3) is used to define N smaller sub-networks. One single base station is then randomly fixed in each sub network. Each sensor node sends its data to the base station deployed inside the sub-network the sensor node is belonging to.

2. Scenario 2:

Case 1: The entire network is considered. N mobile base stations are deployed randomly. Then, the base stations start to move inside the area of interest following the random waypoint model (Johnson & Maltz, 1996). At the beginning of each round, each base station moves 60 m.

Case 2: N sub-networks are defined using the graph-partitioning algorithm and one single base station is randomly deployed in each sub network. Then each base station moves 60m each round. The base station cannot go outside the area of the sub-network it belongs to. This area is represented by a disc with the geographic centre of the sub-network as centre and the distance between this centre and the farthest sensor (belonging to this sub-network) from it as radius.

3. Scenario 3:

Case 1: The entire network is considered. N mobile base stations are deployed randomly on the periphery of the network. Then, the base stations start to move along the periphery. In one round each base station moved 60 m.

Case 2: The graph-partitioning algorithm is used to define N smaller sub-networks. One single base station is randomly deployed on the periphery of each sub network. Then each base station moves 60m each round on the periphery.

We consider that the time required by a base station to move to its next position is negligible compared to a round duration.

Several simulations are then run to compare the network lifetime in the two different cases of each of the three different scenarios.

Simulation results are presented in fig. 5, 6 and 7. They respectively compare the performance of the different base stations deployment strategies in the case of partitioned and non-partitioned network (scenario 1, 2 and 3).

First, let's notice that the simple use of multiple base stations enhances the network lifetime (with and without partitioning). Indeed, the network lifetime increases proportionally to the number of base stations because the distance between the nodes and their correspondent base stations is shortened. Second, it can be seen that moving the base stations clearly prolong the operation of the network. In fact, figures show that the network lifetime is much longer when the base stations are moving (scenario 2 and 3 with or without partitioning) than when they are fix (scenario 1). This result is valid with or without partitioning.

Third, enhancements of the network lifetime can be observed in the case of partitioned large-scale WSNs compared to non-partitioned ones in all the scenarios. But the enhancement is the most significant in the third scenario. This was expected as when one base station is moving along the periphery of each sub-network, the energy consumption is obviously much more distributed over the sensors than when all the base stations are moving along the periphery of the whole network. The nodes that are the closest to the base stations are logically the ones who die first because they not only send their own data but also relay the data of all the nodes in the network. In scenario 3, the nodes who die first in the case of non-partitioned network are the nodes situated all along the periphery whereas in the case of partitioned network, they are the ones situated along the peripheries of the different sub-networks. Then, in this scenario, using the graph partitioning technique to deploy the base stations distributes the load relay and decreases the average distance between the nodes and the base stations. Indeed, the improvement of the network lifetime of the partitioned network is much more important when the number of base stations (or sub-networks) increases.

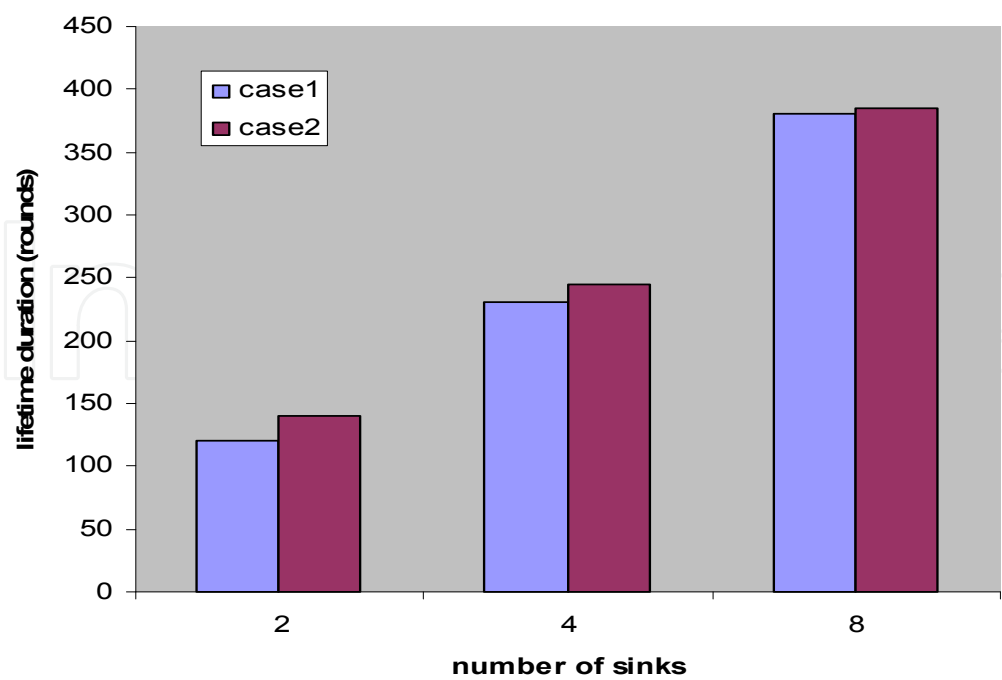


Fig. 5. The network lifetime in the scenario 1.

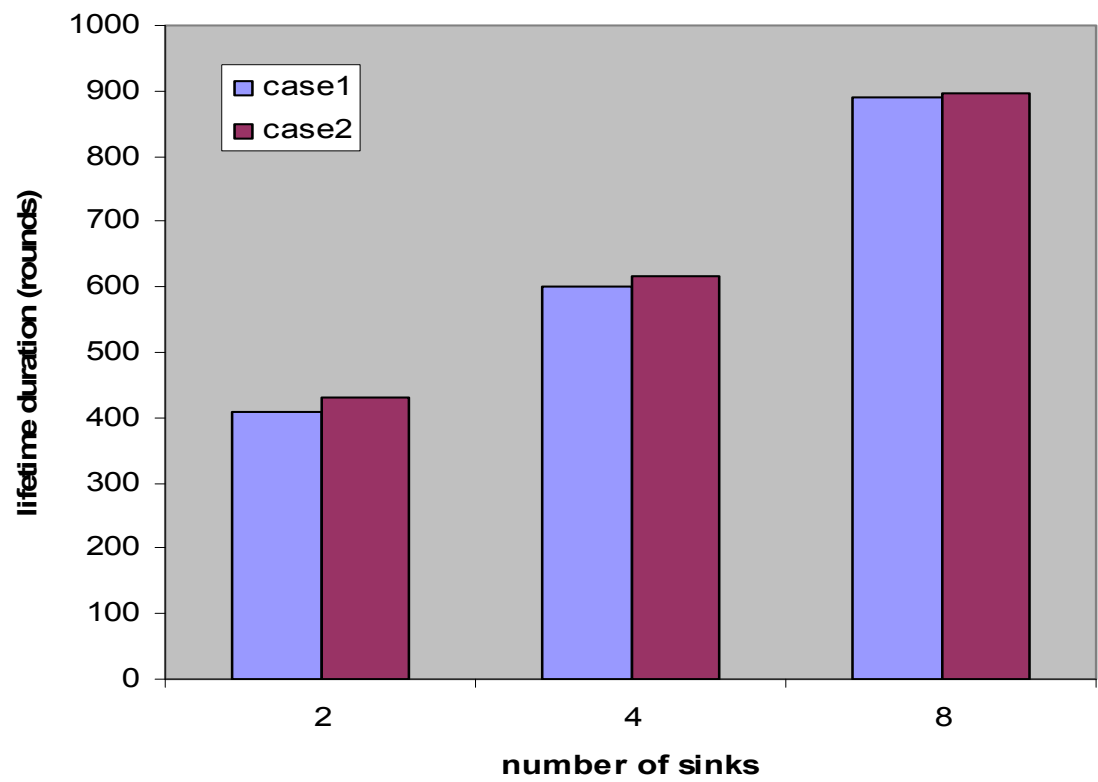


Fig. 6. The network lifetime in the scenario 2.

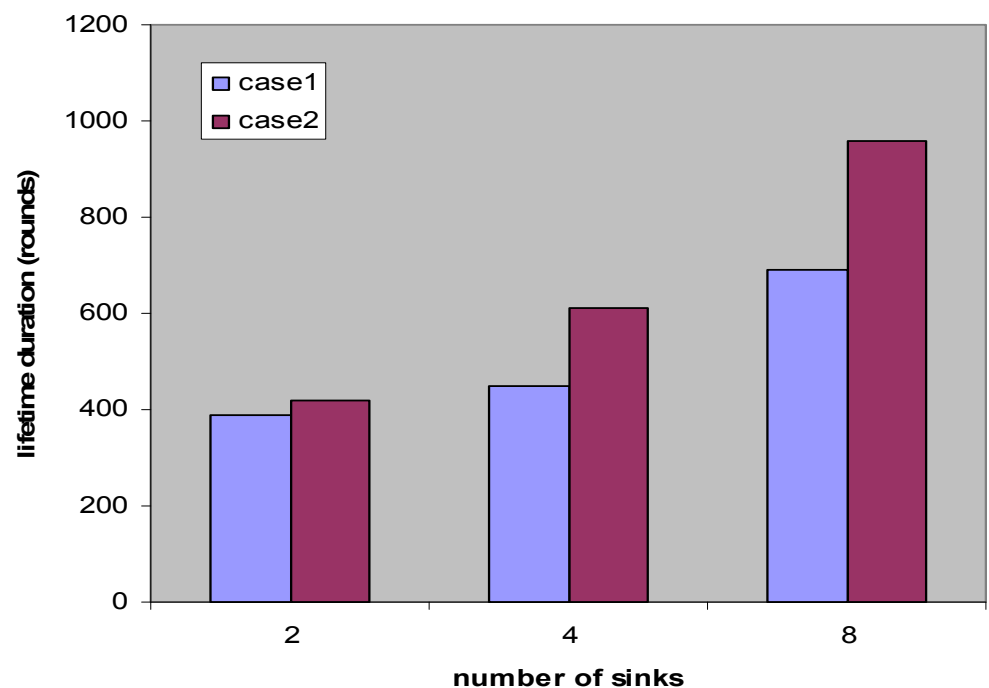


Fig. 7. The network lifetime in the scenario 3.

In the first case of the first scenario, base stations are randomly placed. Hence, they can be in some cases grouped in a small space. As a consequence, the distance between a node and the closest base station may not be really shortened. Whereas, in the second case, where we limited the area in which each base station can be deployed, by partitioning the network into sub networks, this distance is almost always shortened. This can be much more efficient when the base stations move (scenario 2) since the base stations in both cases have the same velocity (60m/round).

However, we notice, from fig. 5 and fig. 6, that the improvement is not so spectacular. This can be explained by the fact that when dividing the network into independent sub-networks, some nodes are bound to send their data to the base station deployed in the sub-network they belong to whereas they are closer to a base station deployed outside (in an other sub-network).

7.2 Inter-Cluster Heads Communication

In this section, we focus on the performance evaluation of the optimization scheme presented in section 4.4 and which manages the communication between Cluster Heads within each sub-network to efficiently transmit data toward base stations. The optimization problem is solved using specific heuristics and several simulations were run over Matlab.

Since the same optimal routing process is used in each of the sub-networks, we limit here our simulations to one single sub-network. We consider then a circular sub-network with radius equal to 100m. Cluster Heads and Sensing nodes are assumed to have a maximum communication radius of 80m and 20m respectively. We assume that nodes are, initially, distributed in a random fashion over the sub-area and that the clusterization is based on neighborhood. Feasibles sets are then randomly generated in each cluster of the sub-

network. One base station with no energy constraints is deployed and randomly placed on the periphery of the area.

The same initial energy is assumed for all Cluster Heads and is equal to 1000 J unit. The same initial energy is also assumed for all Sensing Nodes and is equal to 50 J. Power consumption at the Sensing Nodes is 10 μ W.

The following values are considered for energy dissipation at Cluster Heads.

E_{elec} = 50nJ/bit in the transmit circuitry and

ϵ_{amp} = 100pJ/bit/m² for the transmit amplifier.

γ = 50nJ/bit for the aggregation energy consumption.

We assume the data aggregation ratio β = 25% and a Sensing Node data rate equal to 160bit/s. Figures are obtained by averaging simulation results for a large number of scenarios. For each scenario, a different random node layout is used.

Fig. 8 illustrates the normalized sub-network lifetime. As depicted, the numerical resolution of the proposed model quickly converges to an optimal solution.

To study the effect of the sub-network composition and topology on its lifetime and the interactions between the inter-cluster and intra-cluster communications, we study the scenario where the size of the clusters vary while the number of cluster heads is kept constant. When running the simulations, we randomly generate feasible sets for each cluster. The number of feasible sets in a cluster is randomly chosen. The number of cluster heads is fixed at 20. Initially, we randomly generate the number of sensing nodes in each cluster while keeping the average number equal to 3. Then, we increase the number of sensing nodes similarly in each cluster until it reaches 18 (average size).

The results are presented in fig. 9, which illustrates a sub-network lifetime evolution when increasing the clusters' size and keeping the number of cluster heads constant.

It can be seen that the sub-network lifetime decreases as the clusters size increases. This is expected as when the cluster size increases, the corresponding cluster lifetime increases as well. Hence, each cluster head will spend more time performing both its neighbor's data relay and its own cluster management (its two roles simultaneously). As a result, it expends more quickly its energy which leads to network death in shorter time.

To further explore the performances of the proposed inter-cluster head communication scheme, we propose to study the influence of the clusters lifetime on the choice of the routes to deliver the data from each Cluster Head to the base station. An efficient routing scheme should alleviate from relaying tasks cluster heads with long clusters lifetime since these cluster heads will spend longer time and then much more energy to manage their clusters than those with short cluster lifetime. To this end, we voluntarily generate clusters with considerably different lifetimes (through different sizes). This makes the corresponding clusters' lifetime standard deviation be large.

After several simulations, we compute the different cluster head lifetime and we remark that the corresponding standard deviation is considerably small (3.2% of the whole sub-network lifetime). This result proves that the majority of cluster heads die approximately at the same time. This also proves that flows are fairly distributed over the different cluster heads proportionally to the residual energy available at each one of them and also with considering the lifetime of each cluster i.e., proportionally to their role in the sub-network. The objectives of the proposed schemes are obviously attained.

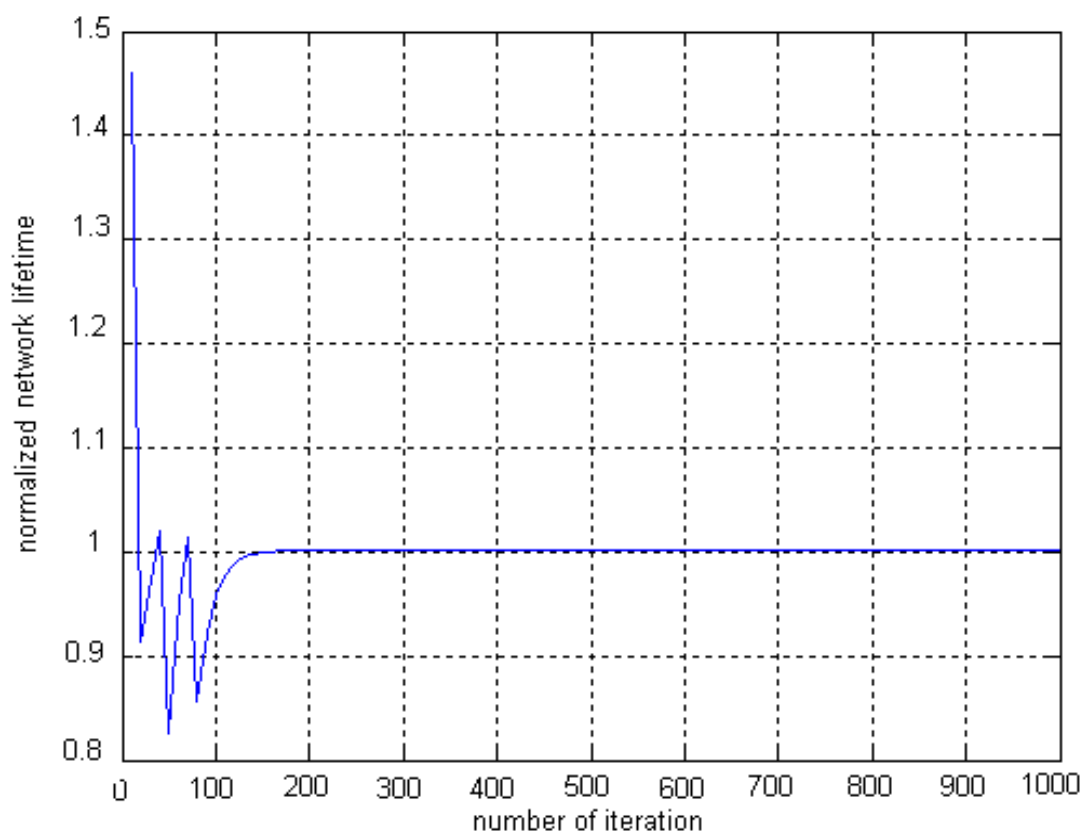


Fig. 8. Lifetime convergence.

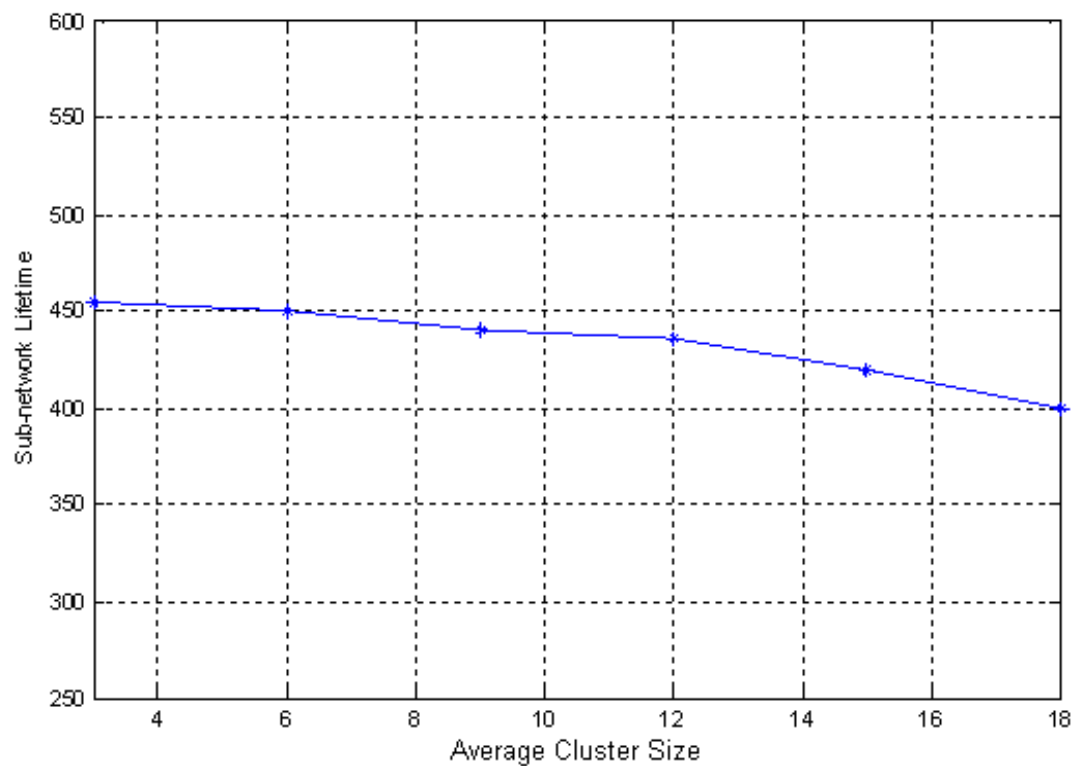


Fig. 9. Sub-network lifetime as a function of the clusters size.

8. Conclusion

The use of multiple mobile base stations in large-scale wireless sensor networks is necessary in order to cover large areas and to minimize energy consumption for data transmission operations. In this chapter, we proposed an energy efficient usage of multiple, mobile base stations to increase the lifetime of a two-tiered large-scale Wireless Sensor Network. Our approach uses a graph-partitioning algorithm to decompose the underlying network into balanced sub-networks. The energy usage is then optimized in each sub-network independently but in the same way using efficient base stations placement techniques that are optimized for small-scale WSNs. Performance results have shown that the proposed technique considerably enhances the network lifetime particularly when the base stations are moving along the periphery.

We have further proposed an optimal multi-hop routing scheme used within each sub-network independently to efficiently manage the communication between the Cluster Heads so that the entire network lifetime is elongated. Different strategies can be used, inside clusters, to manage intra-cluster communications. The proposed scheme simply adapt and fairly distribute the relaying flows according to Cluster Heads residual energy and their corresponding Clusters' lifetime duration, so that Cluster Heads with critical energy situations are alleviated from relaying operations. Simulation results have shown that we can compute a near optimal solution of the routing matrix that defines the optimal flow routing.

The overall dynamic framework that combines the above two schemes has been then described. It is defined as a cyclic algorithm that allows dynamic adaptation of the optimization process according to the current status of the whole network.

Using the graph-partitioning approach to improve energy consumption in large-scale WSNs is promising. We will focus in complementary and future work on more elaborated approaches for optimal multiple mobile base stations placement and WSN partitioning. In addition, efficient tools should be proposed to determine the optimal number of partitions and base stations to be used according to the WSN characteristics, applications' requirements and financial costs.

Moreover, we plan in future work to investigate further the mathematical resolution of the optimization algorithm corresponding to the inter-Cluster Head communication. The effect on energy consumption of the overhead generated by this scheme needs to be more deeply explored.

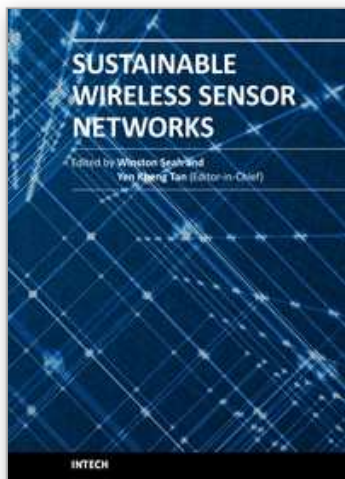
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Wireless Sensor Networks came into prominence around the start of this millennium motivated by the omnipresent scenario of small-sized sensors with limited power deployed in large numbers over an area to monitor different phenomenon. The sole motivation of a large portion of research efforts has been to maximize the lifetime of the network, where network lifetime is typically measured from the instant of deployment to the point when one of the nodes has expended its limited power source and becomes in-operational “ commonly referred as first node failure. Over the years, research has increasingly adopted ideas from wireless communications as well as embedded systems development in order to move this technology closer to realistic deployment scenarios. In such a rich research area as wireless sensor networks, it is difficult if not impossible to provide a comprehensive coverage of all relevant aspects. In this book, we hope to give the reader with a snapshot of some aspects of wireless sensor networks research that provides both a high level overview as well as detailed discussion on specific areas.

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