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Color Restoration of Aerial Photographs

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1. Introduction

A non-uniform distribution of illumination on a negative is provoked by direct and indirect illumination, atmospheric factors and construction of lenses. The effect in aerial photographs can be perceived more easily in photo-indices and mosaics. Often it is attributed to vignetting. However, the direction of illumination due to the position of the sun and atmospheric factors provoke an additional effect that is not radially symmetric to the center of the photograph. This compound effect can appear in any photograph scale.

These problems that were well resolved with the use of filters for haze or anti-vignetting in black&white photographs, are now becoming more critical with the current wide use of color photographs and the increasing use of orthophoto-maps produced with those photographs.

There was also the adaptation of the production methodology of the orthophoto-maps, which in the past demanded that each sheet be produced with just one photograph, but which nowadays, by using the techniques of digital image processing, can allow mosaics of two or more photographs. There is a demand nowadays for seams not to be apparent because of the common differences in tones that exist between neighboring photographs.

The techniques that are already available can resolve various problems, such as the reduction of clearness because of haze from sun reflection, bright areas (hot spots) and vignetting effect; with digital image processing for commercial programs (Nobrega & Quintanilha, 2004; Li et al., 2004a; Wu & Campbell, 2004; Paparodis et al., 2006), but the results are not always acceptable, because the seams are visible or because artifacts appear. On the other hand, there are a lot of research studies and methods being developed that have presented good results and can be incorporated into commercial programs. Some of these methods are discussed in LI et al. (2004a).

This chapter is divided into three main parts: the first one shows the causes of non-uniform illumination in aerial photographs; the second one shows the practical applications of some methods; and the third one presents the results.

Initially, the correction of the vignetting effect is presented by a simple formula and the haze effect in high altitude photographs with color transformation. After that, a method is developed based on masks that is intended to correct the combined illumination degradation effect of vignetting with the bi-directional reflectance distribution function

(BRDF) in color aerial photographs. The manipulation of histograms and the Kries hypothesis are showed for color transformation applied to aerial photographs.

The results are discussed in terms of visual quality and processing time.

2. Non uniform illumination in aerial photographs

The non uniform illumination in aerial photographs originates in the vignetting effects, directional scattering of solar illumination in the presence of haze and the surface bidirectional reflectance.

Moreover there are other factors that can reduce the quality of aerial photographs during their execution, such as clouds or shadows from clouds, shadows from topographic elevations or buildings, reflection from the sun in water bodies, smoke, haze and the quality of the optical system and the film. Analogical aerial photogrammetry developed ways to avoid or partially correct those problems with the use of devices like filters and special films, aside from adequate flight planning for each region and season of the year.

Nowadays, some of these problems, like the reduction of clearness by haze, reflexions from sunlight, shiny areas (*hot spot*) and vignetting, can be solved, at least partially, with digital image processing programs (Nobrega & Quintanilha, 2004; Lamparelli et al, 2004; Silva & Candeias, 2008; Li et al., 2004a). Other aspects are more complex, like the elimination of cloud shadows, and they are still being studied (LI et al, 2004b).

2.1 Vignetting effects

The vignetting effects come from the non-uniform illumination that passes through a lens system until it reaches the negative, where the amount of light is greater in the center and diminishes at the borders. The effect is radial and symmetrical in the center of the photograph, the borders become darker, and in the case of colored photographs, they also become bluer. This problem is greater for wide angle cameras. Figure 1 presents an example of the vignetting effect in black and white and color photograph.

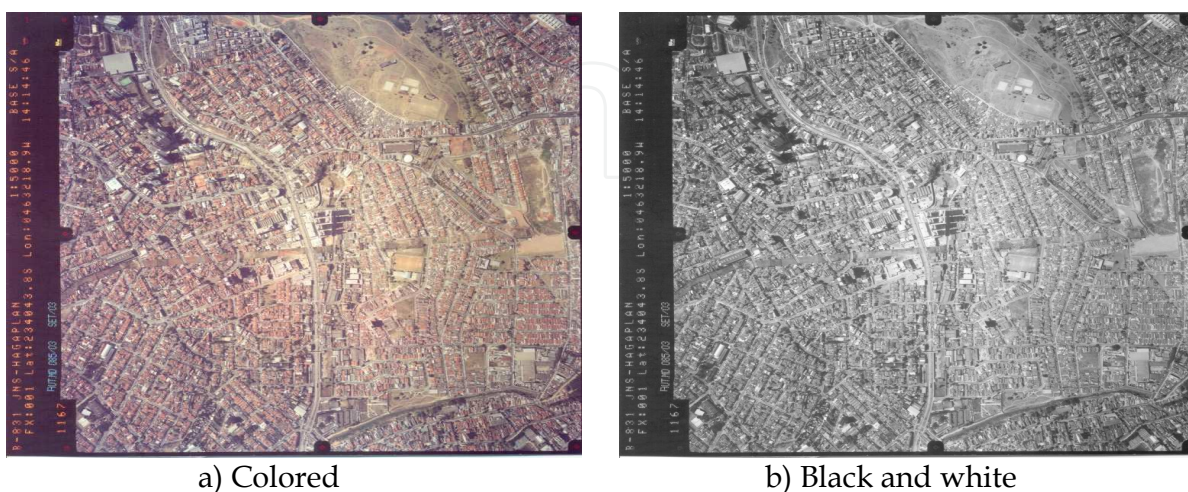


Fig. 1. Photograph with vignetting effect obtained with wide angle camera.
(Photograph: Base Engenharia)

As the effect is symmetrical in relation to the center of the photograph, it can be mathematically corrected. Equation 1 is a very used function to correct this problem

$$I(b) = \cos(b)^n \quad (1)$$

Where: I is illumination which reaches the negative
 b angle between optic axis and light ray
 n varies from 2.5 to 4 (Slater, 1983; Kraus, 1997).

Equations like the one above were used also by HOMMA et al. (2000); Homma et al. (2000); Lamparelli (2006) for correction of the vignetting effect in aerial photographs.

2.2 Effects of atmospheric radiance in aerial photographs

The effects of atmospheric radiance in aerial photographs are complex and they are caused by camera altitude, type, size, concentration and distribution of the atmospheric aerosol, sighting angle, height and azimuth in relation to the sun (Slater, 1983). They can be uniform or non-uniform in the whole area of the photograph. Normally, for photographs from great heights the uniform effect is attributed to the haze and the non-uniform area is related to BRDF (Bi-directional Reflectance Distribution Function) and variations in the type of haze (Paparoditis et al., 2006; Wu & Campbell, 2004).

Figure 2a shows the geometric elements of an aerial photograph that will be useful for the discussion of this study: the EC (Exposition Center), the Nadir, the solar height angle, sun rays indicated by arrows and the camera viewing angle. In Figure 2b, the solar azimuth and the direction of the illumination in relation to the EC are shown.

In the next section we will analyze the effects of atmospheric radiance in aerial photographs of low and high altitude.

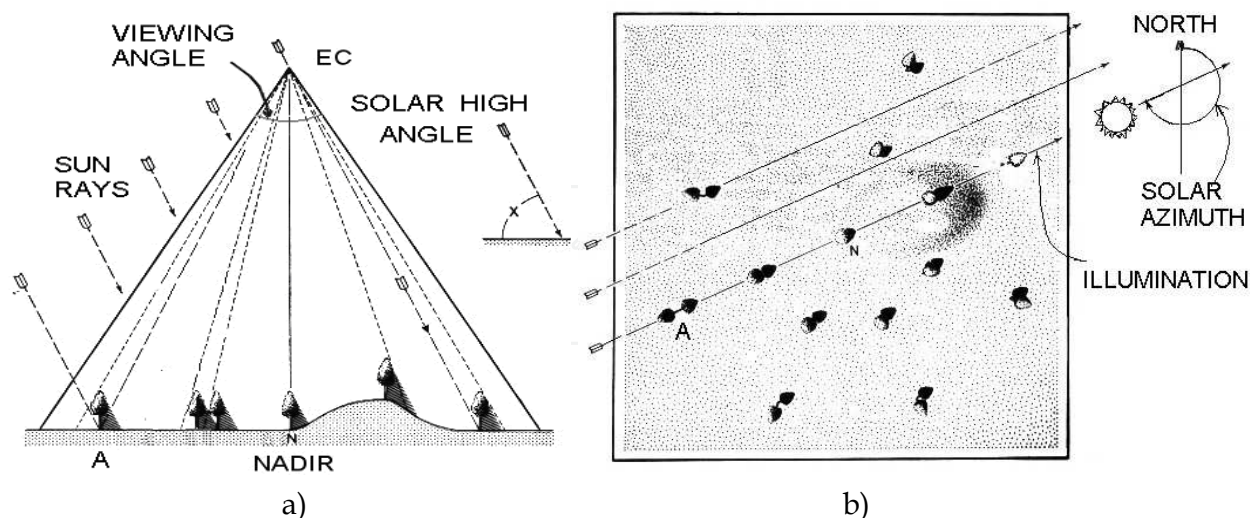


Fig. 2. Geometry of solar illumination on vertical aerial photograph

2.2.1 Haze effect

A well known effect of haze in photogrammetry is the reduction of contrast in photographs taken at high altitudes and in the case of colored photographs the appearance of a uniform

blue tone (Figure 3). This effect is produced by light scattering in the atmosphere even with a clear sky and it is increased in the presence of a dry or humid haze. As a blue light has a higher index of refraction, its scattering is greater and it becomes more visible (Slater, 1983; Fiete, 2004). The reduction of the contrast is significant and reduces the visualization of details of the images (Kraus, 1992).

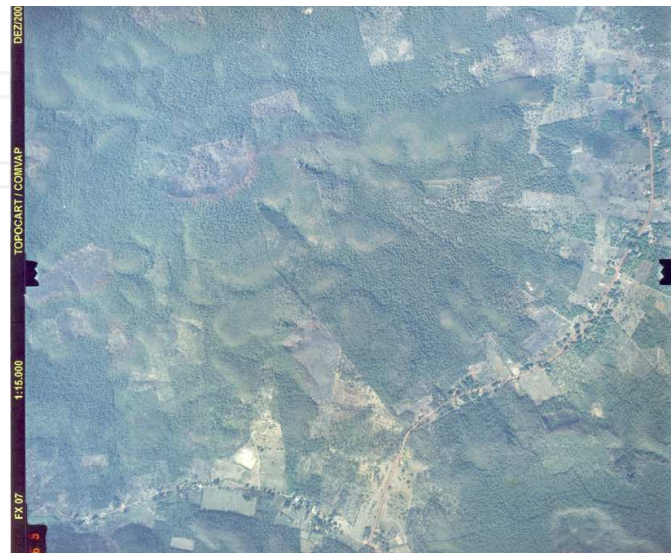


Fig. 3. Bluish color Photograph due to the presence of haze in the atmosphere (Photograph: TOPOCART S/C)

2.2.2 Bright areas

Bright areas, more known as *hot spots*, are the effect caused by the non-visualization of object shadows due to the position of the observer in relation to the sun. This type of bright area does not have to be confound to specular reflection which will be discussed in the next section.

When the sun is directly behind the EC or the observer, a great portion of the landscape will be visualized with direct lighting, and the reflectance will tend to be greater. At the same time the shadows are covered by the height itself of objects like buildings and trees. This effect is due to Paparoditis et al., 2006; Beisl & Woodhouse, 2004). Figure 4

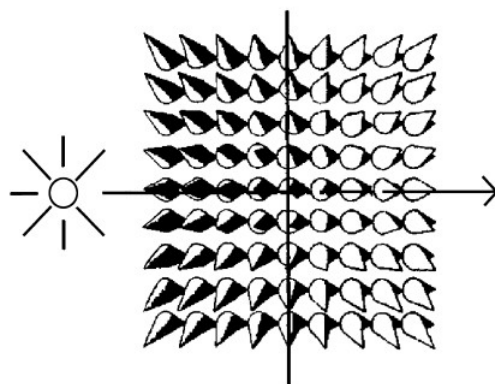


Fig. 4. The brighter area, in the right side of the figure, is in opposite side to the sun due to BRDF. (Tuominen & Pekkarinen, 2004).

illustrates the effects of direct illumination in uniformly spaced trees, which causes an illumination gradient. The sun is on the left in relation to the center of the photograph., so the illumination is darker. On the opposite side, on the right, the BRDF effect occurs and the illumination is brighter.

The BRDF evaluates the reflectance of a surface and depends on the direction of the irradiant flux and the direction of the reflected flux detected (Slater, 1980). This evaluation considers the height angles and the sun azimuth, the angles of the surface on which the flux focuses, the orientation angles and the wave length of the visible light. The calculation of the BRDF is complex and is often used in illumination models, the greater difficulty being the need for information about the reflectance and shape of the objects in the terrain, that are not easily available. As an alternative, simplified or empirical functions are used to estimate the effects of the BRDF in aerial photographs (Beisl & Woodhouse, 2004).

The effects of the BRDF have an impact in the quality of the images in the same magnitude order as the atmospheric effects (Beisl & Woodhouse, 2004), including the haze.

The shape of the hot spot is normally reported as a bright circular area or a peak (Asrar, 1989; Beisl & Woodhouse, 2004), but as can be seen in the illustration of Figure 4 and the examples in Figure 5, the lighter areas do not have a regular circular shape. In vertical images it always appears when the solar zenithal angle is smaller than the sight angle camera.

The black circles on figures 5a and 5b are plotters of viewing angles with a 10° interval and zero at center, showing the subjective visualization of the BRDF effect. The sun position was known from flight data so that the arrow is pointing to the sun and the center of the white circle coincides with the solar zenith angle. These figures also help the visualization of the directional spreading of the haze effect. As will be seen in section 2.2.4 the haze increases the BRDF effect.

2.2.3 Points of specular reflection

The bright peaks, as seen in left side of Figure 5b, can be caused by the specular reflection of the sun in water bodies or metallic rooftops. They are also some times called hot spots in the literature, but they occur in the same side of the sun in the image. That is why in this chapter we will call them of points of specular reflection.

Specular reflection points appear when the solar high angle is bigger than half of the opening angle of the camera and the projection of the sun rays reaches a reflective surface. Using the geometry in Figure 2 this reflection would occur in point A. When using a large angular camera there can be reflection points with the sun height at over 45° , which is why it is necessary to take special care on photogrammetric flights done around midday, when the sun is higher. In the photograph of figure 5b there are both specular reflection points (pointed by arrow) and hot spots (neighborhood of the white circle), positioned on the opposite side in relation to the center of the photograph.

2.2.4 Directional spreading of light of the haze effect

Some authors noted that there are other factors besides the BRDF that can change the illumination in photographs. Kraus (1989) shows that the photographs taken in the Southern

and Northern hemispheres present systematically brighter areas in the North and South, respectively. Asarar (1989) shows that there is more radiation spread in the direction close to the incident light that must not be confused with the hot spot effect.



a)



b)

Fig. 5. White circle on center of hot spot and arrow pointing to sun. a) Only hot spot, b) Also with specular reflection on side of sun. (Photograph: Base Engenharia)

Silva & Candeias (2009) have reproduced the work of Hall (1954), which allows the identification of the center of bright areas which is the effect of haze scattering and a function of the angle of the sun light and viewing angle of camera.

The radiance reaching the sensor is the sum of spectral reflectance and thermal radiant surface, multiplied by the spectral transmittance of the path in the atmosphere (Slater, 1980).

The product is added to this spectral radiance upward along the route. Thus the formulation presented by Hall contains simplifications and does not take into account the multi-scattering. However, their approach is very enlightening and shows that the flow or final radiance is a function of the scattering coefficient and the distance traversed by the flow.

Hall (1954), using G. B. Harrison's formulas, relates the haze factor to the height of the sun. To do that is need consider the brightness of alight pulse sweeping a vertical plane as in the Figure 6. The geometric elements of figure 6 involved in the formulas are: the sun zenith angle θ , the a angle Φ that makes a haze cone with the sun ray, the viewing angle β , the exposition center (EC); altitude of flying h . The points on the ground A and B have viewing angles β_a and β_b , respectively, and point N is in Nadir.

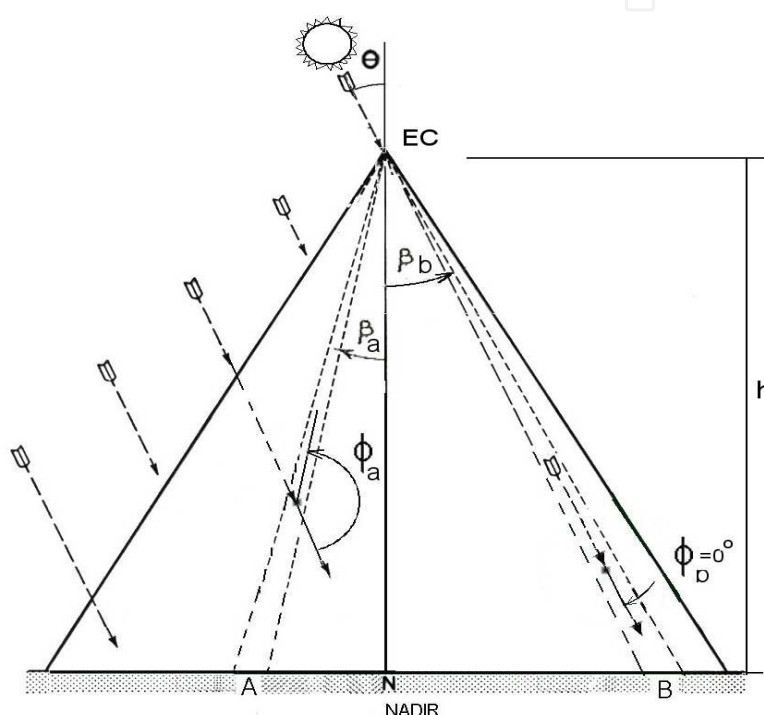


Fig. 6. Geometrical elements involved in analysis of haze factor.

The percentage of haze factor at β angle can be estimated in aerial photographs by:

$$H\beta = 100 \times (H_B\beta) / GB\beta \quad (2)$$

Where: $H_B\beta$ is the brightness of an elemental cone of haze which makes an angle β with the vertical line or nadir

$GB\beta$ is the brightness as seen through the haze of a horizontal white diffuse reflector on the ground intercepted by the cone.

The brightness of a cone of haze at angle β is given by:

$$H^B\beta = Af(\phi) \frac{\cos\theta}{\cos\beta + \cos\theta} \left[1 - e^{-\sigma h(\sec\beta + \sec\theta)} \right] \quad (3)$$

Where: σ is the coefficient of total scattering in the ft^{-1} unit.

$f(\Phi)$, is the scattering phase function, which describes the angular distribution of scattered radiation (Φ here is the scattering angle). The scattering phase function $f(\Phi)$ depends on the density and physical characteristics of the particles and the wavelength. As you increase the size of the particles there is a stronger forward scattering ($\Phi = 0^\circ$) and a smaller but still significant back-scattering ($\Phi = 180^\circ$).

Doing the second part of left side of (3) as:

$$G = \frac{\cos \theta}{\cos \beta + \cos \theta} \left[1 - e^{-\sigma h (\sec \beta + \sec \theta)} \right]$$

(4)

We now have the brightness of the haze as:

$$H^B \beta = A.f(\phi).G$$

(5)

The brightness of a white reflector is given by:

$$G^B \beta = A \frac{\cos \theta}{\pi} \left[e^{-\sigma h (\sec \beta + \sec \theta)} \right]$$

(6)

The haze factor in percentage is therefore:

$$H\beta = 100\pi f(\phi) \frac{\left[e^{\sigma h (\sec \beta + \sec \theta)} - 1 \right]}{\cos \beta + \cos \theta}$$

(7)

Where A is a constant and depends of sun illumination.

The locus of G with respect to β is a smooth curve with minimum at $\beta = 0$ and symmetrical of about OY .

The curve of $H^B \beta$ for $\theta = 40^\circ$, $\sigma = 0.00005 \text{ ft}^{-1}$, $h = 16000 \text{ ft}$ is shown on Figure 7. The value of σ , estimated at $5 \times 10^{-1} \text{ ft}^{-1}$ corresponds to the daytime visibility of 20 miles. The curve of $f(\Phi)$ against Φ is generally U shaped and the values used by Hall are in Table 1.

Φ	0	10	20	30	40	50	60	70	80	90
$f(\Phi)$	0.470	0.400	0.310	0.220	0.160	0.110	0.070	0.050	0.040	0.035
Φ	100	110	120	130	140	150	160	170	180	
$f(\Phi)$	0.030	0.030	0.040	0.045	0.060	0.080	0.100	0.160	0.030	

Table 1. Values of scattering phase function $f(\Phi)$ against Φ used by Hall(1954).

The strong variation over a short range of β in the neighbourhood of $\beta = -\theta$ and $\Phi = 180^\circ$ means a variation which is proportional to the haze lightness that illuminates the corresponding region of the photograph (Hall, 1954).

Figures 8a and 8b show graphs of the haze factor percentage calculated for $\sigma = 0.00005 \text{ ft}^{-1}$, $\sigma = 0.00008 \text{ ft}^{-1}$, $h = 16,000 \text{ ft}$, angles $\theta = 40^\circ$ and $\theta = 60^\circ$. The haze factor is always greater on the side opposite the sun ($\beta = -40^\circ$ in figure 8a). There is a sharp peak when σ increases around $\theta = 40^\circ$. If the semi-lens viewing angle (β) is 45° and $\theta = 60^\circ$ the maximum haze factor would be out of the image. (Figure 8b).

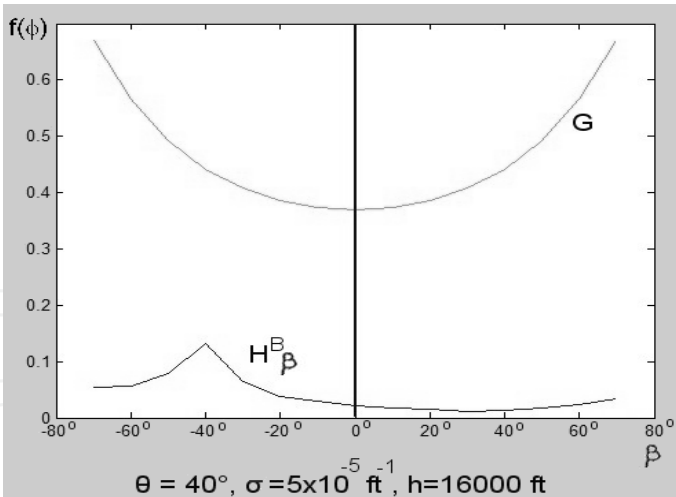
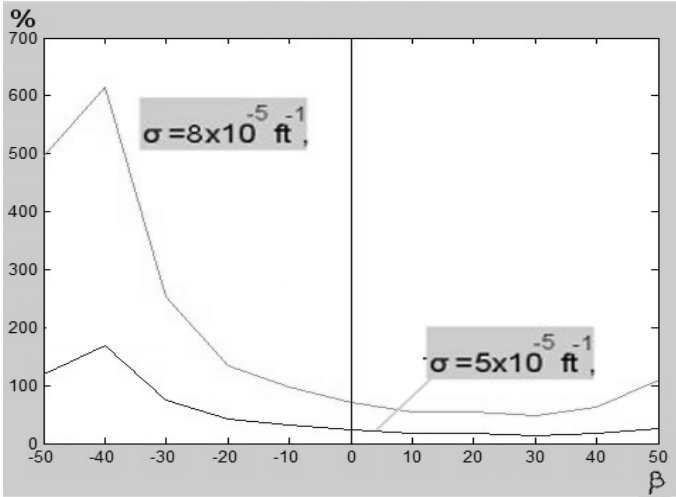
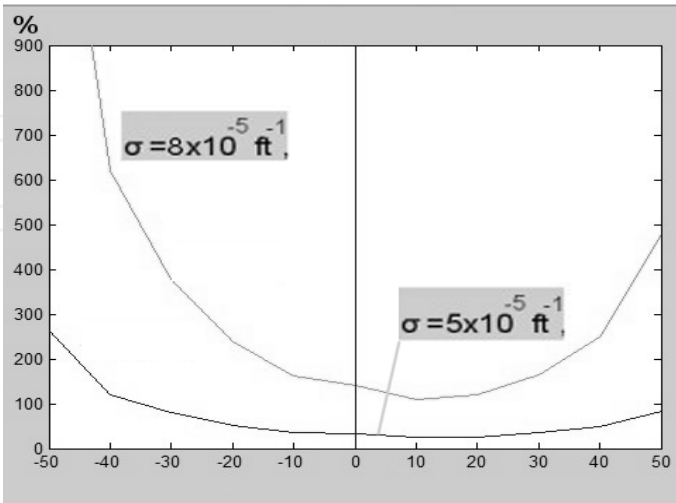


Fig. 7. Brightness curve of the haze ($HB\beta$) with $A=1$, $\theta=40^\circ$, $\sigma=0.00005\text{ ft}^{-1}$, $h= 16,500\text{ ft}$



a)



b)

Fig. 8. Curves of the factor haze percentages with $\sigma = 0.00005\text{ ft}^{-1}$, $\sigma = 0.00008\text{ ft}^{-1}$, $h = 16,000\text{ft}$. a) $\theta = 40^\circ$ b) $\theta = 60^\circ$

With the given formulas it is possible to estimate the positions of the brighter areas and the gradient of change of lighting in the photographs, using data from flying reports and sun ephemeris.

3. Restoration of colors

The colors of objects and landscapes in the photographs altered by any of the various factors discussed above can be restored, at least in part, with the help of processing image methods, so that they are more realistic, more uniform between adjacent photos and more uniform with respect to the frame itself.

In this section some of these procedures will be applied. In photogrammetry and remote sensing the methods used in general are: application of functions to correct vignetting (Homma et al, 2000), models of atmospheric radiation and illumination (Beisl&Woodhouse, 2004), manipulation of histograms (Kraus, 1997; Tuominen & Pekkarinen, 2004; Nobrega & Quintanilha, 2004), restoration with the use of RGB color space, HSI-RGB (Guo & Moore, 1993), use of masks (Li et al, 2004a, Silva & Candeias, 2008), burning and dodging (Reinhard et al, 2002; Li et al, 2004a).

3.1 Restoration of haze

During the taking of the photographs the attenuation of haze effects can be done using a yellow filter placed in front of the lense that absorbs the excess blue light. In digital photogrammetry the degradation, in digitalized images or those obtained directly from a digital camera, can be corrected using radiometric processing functions, color correction or radiometric atmospheric models. Figure 9 shows an original photograph and the result after color casting correction using Kries method explained in section 3.6.

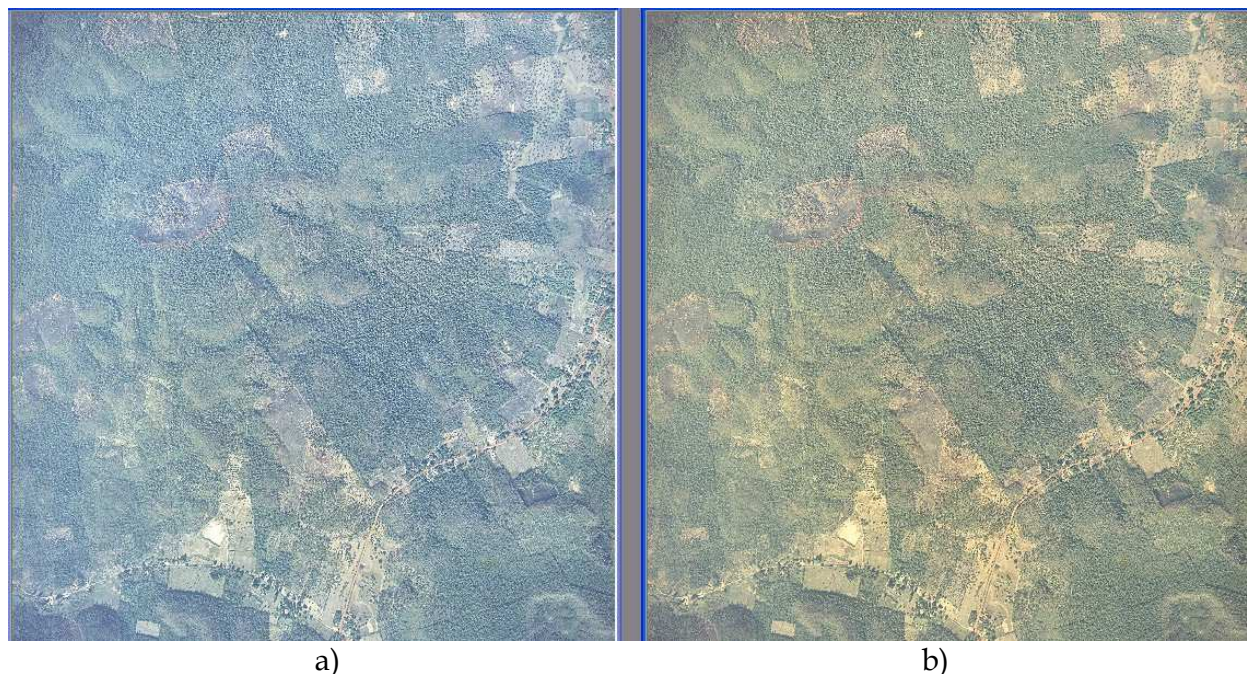


Fig. 9. a) Photograph with uniform haze, b) Photograph processed using Kries method.

3.2 Corrections of specular reflection

Peaks of sun light create white spots or white areas on digital images when the amount of concentrated light exceeds the dynamic range of sensitivity of the CCD sensor. This problem can be avoided with proper planning of the photogrammetric flight, knowing of sun ephemeris and, nowadays, it can be mitigated with the use of digital images with more than eight bits per color channel. Ashikhmin (2002) and Reinhard et al. (2002) can make details visible in parts that are too light or too dark, using algorithms that adapt contrast intervals, to map levels of the original image to the levels likely to be played on the monitor screen or in print.

3.3 Correction by manipulation of histogram blocks

Among the processes that can correct non-uniform illumination in digital images, that are available in commercial programs, the most common is the one that carries out the balancing of histograms between blocks, through homogenization of statistical parameters. The correction is done by dividing the original images into blocks, or into sub-images, calculating diverse statistics as global minimum and maximum averages of each block; and processing the histograms, so that they balance the differences of brightness intensity among the blocks. This method can be used both among photographs of a mosaic and in isolated photographs for correcting vignetting effects, bright areas and BRDF. A description of this method, together with some examples of variation, can be found in Li et al., (2004); Paparodis et al. (2006) and Nobrega & Quintanilha (2004).

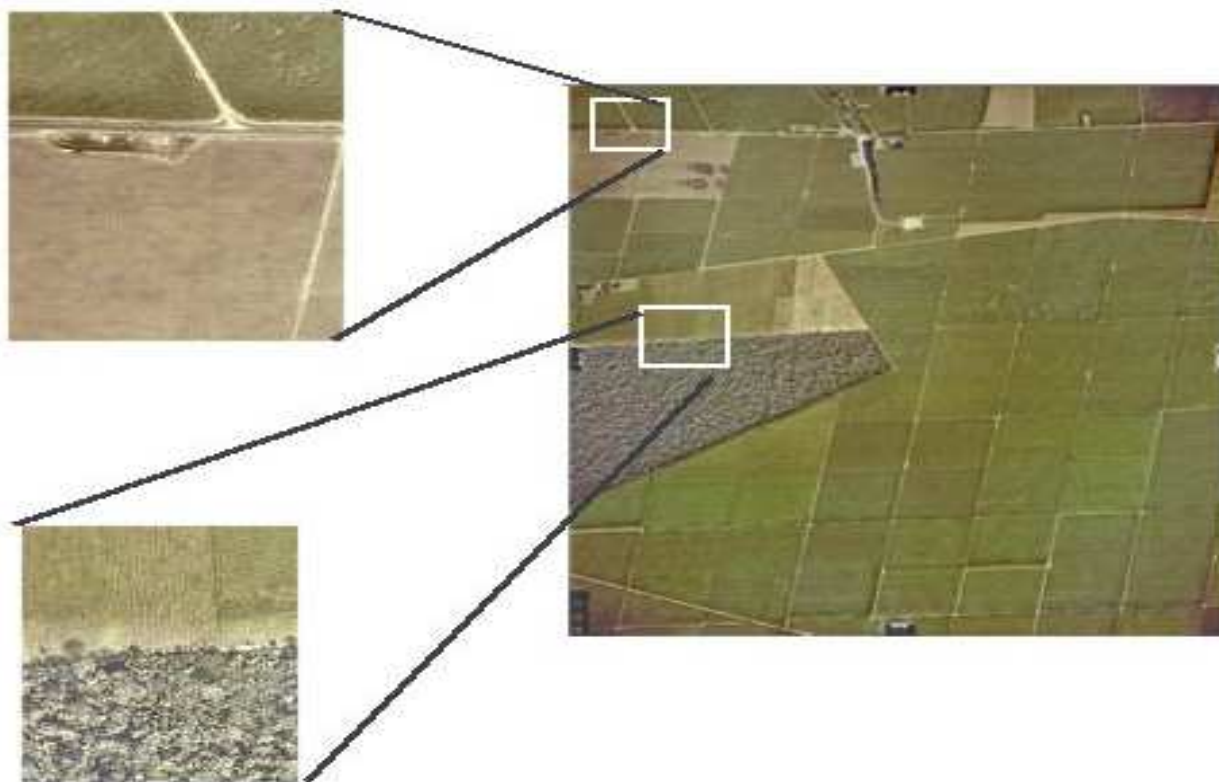


Fig. 10. Photograph processed using histograms blocks balancing, showing transitions between areas with significant tone differences. (Photograph: TOPOCART S/A)

The method, although well diffused, does not always have good results, principally if the photographs, or areas of photographs, have significant intensity differences or abrupt variations in tonalities. This problem can be seen in examples shown in (Nobrega & Quintanilha, 2004; Li et al., 2004a; Wu & Campbell, 2004; Paparodis et al., 2006). Figure 10 shows an example of a photograph processed with this type of manipulation of histograms. The amplified details show the color gradients which appear in the transition zones between clear and dark features in the images, and among different kinds of vegetation.

The algorithms to manipulating of histograms blocks divide the image into sub-images, and after that it calculates parameters such as mean, standard deviation, minimum and maximum gray levels of each color channel and as individual histograms. There is a variation called LRM (Local Range Modification) and the definition is presented in Schowendgert (1997). In this process, after the standardization of histograms, a smoothing process near the edges of each sub-image is adopted to avoid the appearance of breaks in continuity. Thus the maximum (MAX) and minimum (MIN) values are calculated for each vertex of the block, the minimum average (LA, LB, LD, LE) and average maximum values (HA, HB, HD, HE) of neighboring blocks, as shown in Figure 11.

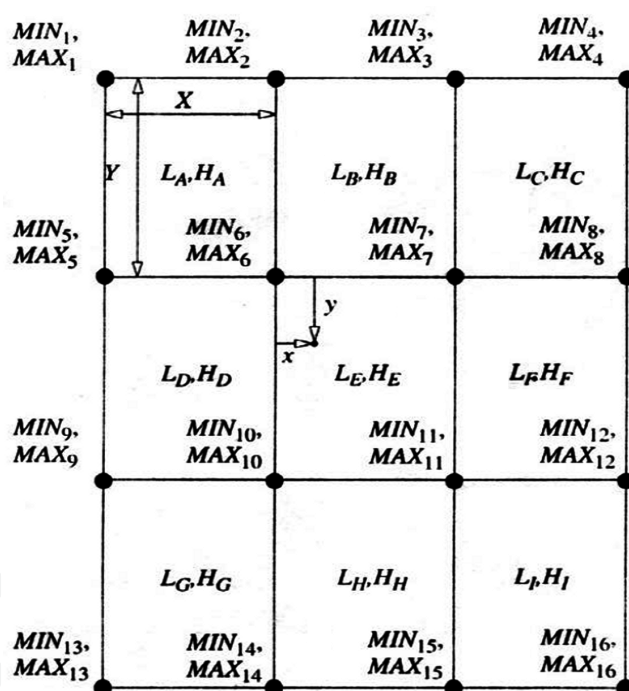


Fig. 11. Blocks and parameters used in the LRM (Schowengerdt, 1997).

The interpolation for the xy position in the above figure uses the maximum and minimum values of the vertices 6, 7, 10 and 11 and provides the values given by the equations below:

$$GL_{\min} = \left[\frac{x}{X} MIN_7 + \left(\frac{X-x}{X} \right) MIN_6 \right] \left(\frac{Y-y}{Y} \right) + \left[\frac{x}{X} MIN_{11} + \left(\frac{X-x}{X} \right) MIN_{10} \right] \frac{y}{Y}$$

$$GL_{\max} = \left[\frac{x}{X} MAX_7 + \left(\frac{X-x}{X} \right) MAX_6 \right] \left(\frac{Y-y}{Y} \right) + \left[\frac{x}{X} MAX_{11} + \left(\frac{X-x}{X} \right) MAX_{10} \right] \frac{y}{Y} \quad (8)$$

Where: GL_{min} = minimum value of brightness of the pixel.

GL_{max} = maximum value of brightness of the pixel

X = dimension of the block columns

Y = dimension of the block in rows

x = column for the position of the pixel in the block

y = row for the position of the pixel in the block

The calculated values are used in the interpolations to get the new gray value image produced:

$$GL' = \frac{255}{GL_{max} - GL_{min}} (DN - GL_{min}) \quad (9)$$

Where: GL' = new value of brightness to be applied to pixel.

DN = value of brightness of the pixel

This algorithm provides good results but has high computational cost and some variations have been proposed that use only mean and standard deviation compared with a global mean value. In general, all promise gain of brightness for darkened areas and darkening of light regions. This type has been used in commercial programs for balancing color aerial photographs and satellite images and digital mosaics in general. For more details consult Nobrega & Quintanilla (2001).

3.4 Global histogram manipulation

The more common methods of manipulations of histogram are equalization and stretching (or normalization). They are applied for enhance contrast of images. Histogram Equalization seeks to produce a balanced image with a uniform distribution of grey tones. Histogram normalization adopts the normal distribution as the transfer function for the desired image.

Furthermore is possible to change the histogram of an image using the histogram of another image as model. This procedure is called histogram matching and figure 12 shows a example. The histogram of figure 12a is of desired image, used as reference, in figure 12b is the histogram of image to be changed and in figure 12c is the histogram of new image. The final result is very similar to figure 12a.

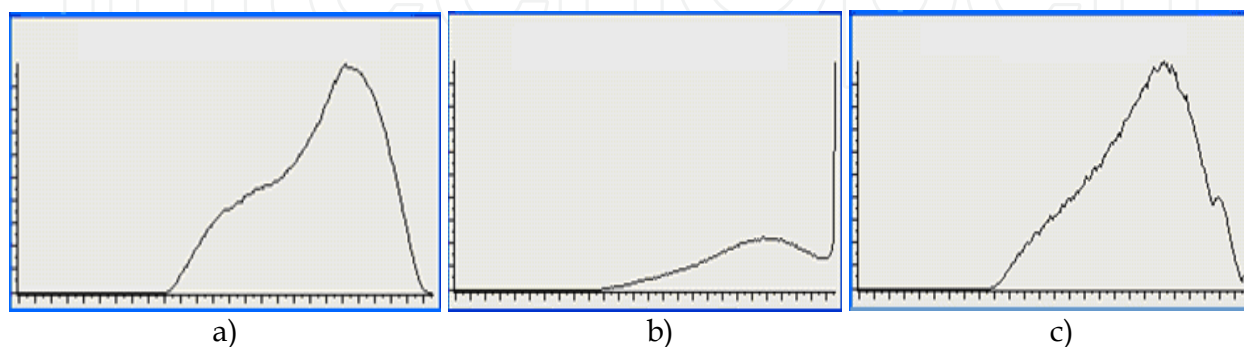


Fig. 12. Example of histogram matching. a) Histogram of reference image, b) Histogram to be changed, c) Histogram changed.

Most of image processing software has the capacity of handle with histograms and change them. More details about theory can be found in (Kraus, 1997; Pratt, 1991).

3.5 Correction with masks

The masks in image processing are binary images or gray tones that are used for delimiting areas where certain operations can be carried out, or to control the degree of processing they can go through. Examples of binary image masks are the delimiting polygons of each of the images that form mosaics. Masks in gray tones are already used by photographers and the graphic industry for attenuating shadows of scenery and environment.

However, as these resources have not been used in photogrammetry, an analysis of the viability of the use of masks is carried out to correct non-uniform illumination in aerial photographs. For this, initially, a complete sequence of a mask construction will be detailed.

A mask should represent the mean illumination intensities of the combined effects of vignetting and DBRF. Considering that the variation in luminosity which reaches the plan of the negative does not vary significantly among the photographs of the same area or when taken in a short period of time, a mask should suffice for processing a group of neighboring aerial photographs.

For the construction of the masks (Figure 13) only one photograph would be used, but the mask can get better if two or more are used, so that the result can be free of differences in the tonality of the scenery. The process can start by two ways: a) profiles of gray values of the image pixels in lines and columns, along the borders, through the center and intermediate regions; b) or using averages values of sub-blocks. This latter process eliminates better the high frequencies. Therefore, when using polynomial regression of a cubic function, as in equation 10, an adequate fitting for a uniform surface is obtained without abrupt changes:

$$Z(x,y) = A + By + Cy^2 + Dy^3 + Ex + Fxy + Gxy^2 + Hx^2 + Ix^2 + Jx^3 \quad (10)$$

Where: x,y = coordinates of the points equivalent to the positions of the pixels or centers of sub-blocks

$Z(x,y)$ = the ordinate, or grey value, in the x,y position

A to J = the coefficients obtained with a sample entry.

The masks can be constructed in accordance with the available resources and the ones used here were obtained by following the steps below:

- Transformation of colored images into gray tones at levels of 0 to 255.
- Division of image forming a grid of 5x5 (25 blocks), trying to eliminate the margins and the fiducial marks.
- Calculation of mean intensity of each of the 25 blocks and registration of the minimum and maximum levels.
- Interpolation of Z values with a cubic or quadratic function.
- conversion to negative image

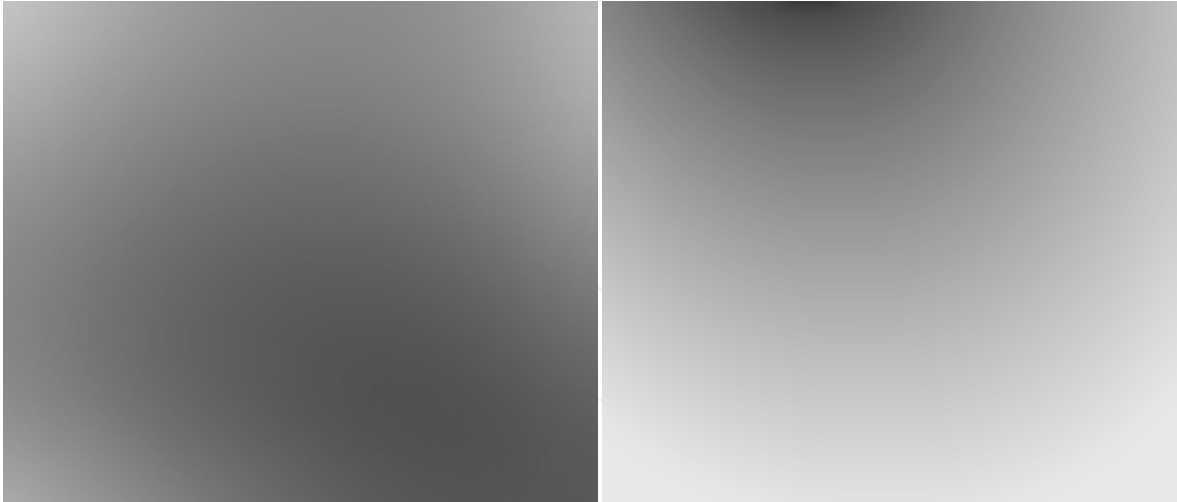


Fig. 13. Examples of masks to correcting illumination intensities.

3.6 Corrections using Kries method

The correction or alteration of colors in digital images can be carried out through several methods using operations in color space and transformations between them, however, a good experience of the human operator is necessary. A method that could be more independent is based on the Von Krie hypothesis.

The Von Krie hypothesis method considers that the primary stimuli of *RGB* color in the retina can be linked to the imaginary stimuli (*XYZ*) by a linear transformation with matrix *M* (Wyszecki & Stiles, 1982). Equation 11 shows the relation of *RGB* with *XYZ*.

$$\begin{bmatrix} R \\ G \\ B \end{bmatrix} = M \begin{bmatrix} X \\ Y \\ Z \end{bmatrix} \quad (11)$$

This hypothesis is commonly used in image acquisition devices (such as cameras and scanners) to correct image lighting (sunlight, incandescent or fluorescent lamps) in a simplified manner, in two ways:

A) white balancing

This method is known as image white balancing

$$\begin{bmatrix} R' \\ G' \\ B' \end{bmatrix} = \begin{bmatrix} kR & 0 & 0 \\ 0 & kG & 0 \\ 0 & 0 & kB \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix} \quad (12)$$

Where $R'G'B'$ is image desired, and RGB is the original image. The coefficients are obtained from the sample initially and then applied to the entire image

$$kR = \frac{R'}{R}; kG = \frac{G'}{G}; kB = \frac{B'}{B} \quad (13)$$

Where R, G, B are the average of the desired area. $R' = G' = B' = 255$, because they correspond to a white area and to images of eight bits per channel.

B) When the lighting is not known

In this case the process is applied in a representative area of the image and the maximum level of intensity in each band is determined. With this procedure $R = \max (R)$, $G = \max (G)$ and $B = \max (B)$ and R', G' and B' are also equal to 255.

In this study the method was applied to change the colors of an image with undesirable color based on another image that shows the desired tone, or even the same image in different areas.

4. Results and discussion

4.1 Vignetting correcting

Vignetting corrretion was presented in Equation 1. The image in grey format is sized for 1/8 of original size, and applied a filter like Gaussian to blur the image and to get the grey levels in the center and the borders. The final calculations use Equations 14 and 15 with the following adaptations: a) consideration of the maximum radius equal to diagonal of image frame and each pixel radius equal distance between pixel and image centre; b) for simplicity, $\cos(b)$ calculation uses the focal length equal to the width of the image; c) the maximum correction occurs at border and at center it is null.

During the calculation the radius is obtained and the correction for each pixel is given by $fcor$. The radius is the distance pixel-center. The gray level correction is:

$$fcor = corr \max * \frac{(1 - \cos \beta)}{(1 - \cos \beta \max)}$$

(14)

Where: $\cos \beta = \cos(b)$ at any point
 $\cos \beta \max = \cos(b)$ at border
The pixel color is corrected by:

$$I(i,j) = fcor + I(i,j)$$

(15)

An example of this final processing is shown on Figure 14b. The calculation of the average gray in a reduced image was 190 in the center and at the edges it was 148, 157, 145 and 147, with an average of 149; factor $190/149 = 1.275$. After applying the corrections the dark border is eliminated.

The Minimum (Min), Maximum (Max), Mean and Standard deviation (Stdev) of the Figure 14 are showed in table 2. The global effect with the vignetting correction is to grow up the minimum and mean and reduce the standard deviation of the result image.

Basic Stats	Min	Max	Mean	Stdev
Fig. 14(a)	22	255	153.014712	34.643259
Fig. 14(b)	77	255	178.653428	30.067176

Table 2. Basic Statistics of Figure 14



Fig. 14. Correction of vignetting effect of left image showed in the right.

For the color photograph (Figure 15a) the calculation by bands was performed: Red, center 200, edges 173, 155, 157 and, 161, average= 161, factor = 1.238; Green, center 184, edges 143, 142, 153 and 140, average = 144.5, factor = 1.273; Blue, Center 166 , edges 147, 141, 139 and 145, average= 143 , factor = 1.161. The result is shown on Figure 15b.

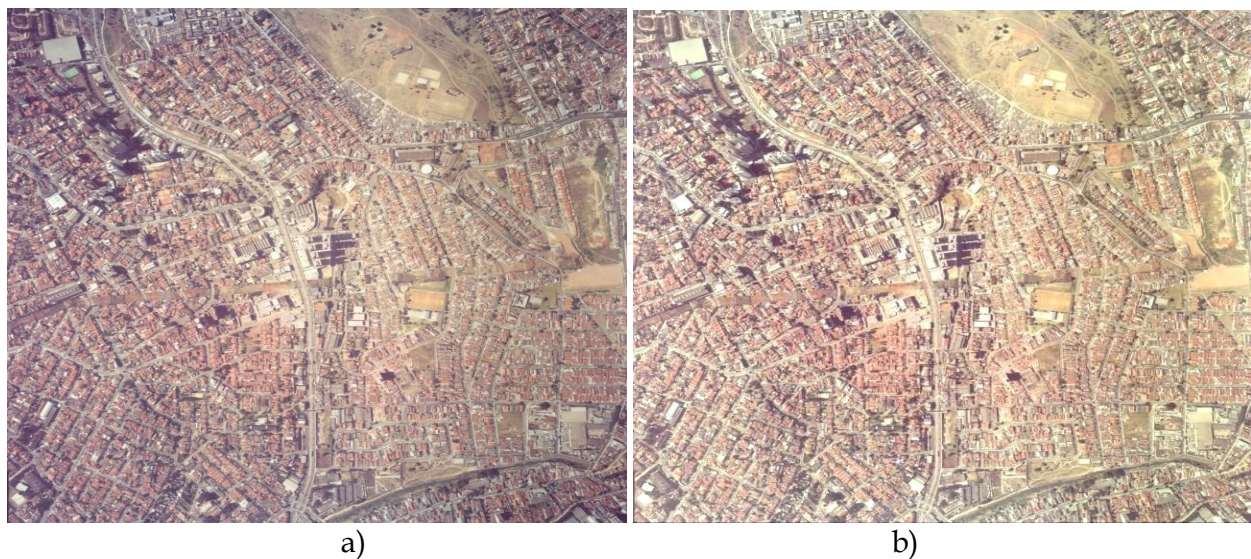


Fig. 15. Vigneting in color photograph a) Original image, b) With Vignetting correction.

Another way of using *fcor* is to create a mask that can be applied to all images in a range of line flight, for example. Thus processing is faster, compared to methods of manipulating histograms, because you just add the masks of each band to the bands of the images.

4.2 Application of masks

One of the processing results with an individually added mask to the RGB bands of Figure 16a, is shown on Figure 16b. The very dark tonality in the inferior part of this figure was corrected. The colors of the darker parts are not well recuperated because they were saturated. This problem will be resolved in section 4.3.

The block balancing method was also applied to the same photograph and the result is shown on Figure 16c, where the mean tonality of the image is more uniform, but the inferior part is still very dark, aside from presenting the artifacts already shown on Figure 10

Table 2 shows the basic statistics of original image, image balanced with mask and with histogram blocks images of Figure 16. Observing the standard deviation (Table 3), it is possible to see that there is more variability of colors in original image and this effect is corrected in the other ones.

The method of mask addition, although it does not introduce artifacts and undesired color transitions, it is computationally more efficient, since the same mask can be used in many photographs taken at a certain interval of flight time, as in the strip (Figure 17). Moreover, the process of adding original image with the mask is quicker than the processing of the multiplications and divisions involved in other methods. For an image of 11,500 x 11,500 (pixels) and blocks of 100 x 100, the total time was 3min 40s with manipulation of histogram blocks, and only 1min 10s with the mask, on the same computer. The preparation time for the mask depends on the program used, but it can be totally automated.

Basic Statistics		
Original	With mask	With block balancing
Band: R Min: 4.00 Max: 255.00 Mean: 139.31 Standard Deviation: 58.64	Band: R Min: 4.00 Max: 255.00 Mean: 149.52 Standard Deviation: 34.82	Band: R Min: 4.00 Max: 255.00 Mean: 135.82 Standard Deviation: 37.63
Band: G Min: 0.00 Max: 255.00 Mean: 136.70 Standard Deviation: 56.47	Band: G Min: 4.00 Max: 255.00 Mean: 148.28 Standard Deviation: 33.64	Band: G Min: 0.00 Max: 255.00 Mean: 133.27 Standard Deviation: 36.87
Band: B Min: 0.00 Max: 255.00 Mean: 117.58 Standard Deviation: 46.76	Band: B Min: 4.00 Max: 255.00 Mean: 136.21 Standard Deviation: 28.97	Band: B Min: 0.00 Max: 255.00 Mean: 116.43 Standard Deviation: 30.90

Table 3. Basic Statistics



Fig. 16. Comparing processed images with mask and histogram manipulation

The basics statistics in Table 4 show that the strip with pre-processed images is brighter (Figure 17a) and it has lesser standard deviation than with rough image (Figure 17b). Qualitatively it can be seen in Figure 16.

Basic Statistics	
With pre-processed images	With rough images
Band: R	Band: R
Min: 57.00	Min: 4.00
Max: 255.00	Max: 255.00
Mean: 164.81	Mean: 128.19
Standard Deviation: 33.79	Standard Deviation: 46.73
Band: G	Band: G
Min: 57.00	Min: 4.00
Max: 255.00	Max: 255.00
Mean: 162.85	Mean: 127.36
Standard Deviation: 31.68	Standard Deviation: 45.96
Band: B	Band: B
Min: 51.00	Min: 4.00
Max: 255.00	Max: 255.00
Mean: 145.13	Mean: 112.01
Standard Deviation: 27.23	Standard Deviation: 35.74

Table 4. Basic Statistics

In Figure 17a some difference of tonality can still be seen in the stick zones. This could be due to the use of only a single photograph for preparing the mask and the influence of the features of the land as the vegetation. Ongoing tests show that an average mask obtained from more than one photograph represents, with more accuracy, the combined illumination effects of the BRDF, haze and vignette.

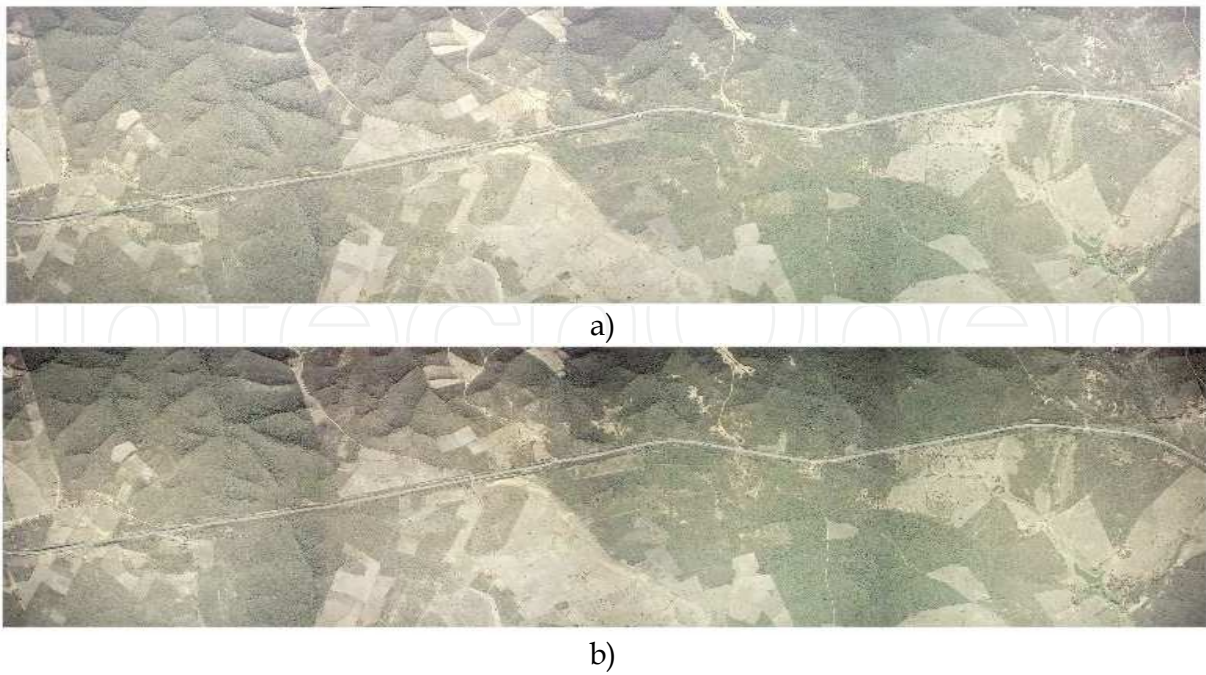


Fig. 17. Example of a mosaic strip. a) Pre-processed with masks, b) With rough images. (Photograph: TOPOCART S/ A).

However, the greater uniformity of tones observed in the images processed with masks is already enough to significantly improve the quality of a mosaic that is reprocessed with block balancing, as shown on Figure 18a, while on Figure 18b there are still areas with more shadows.

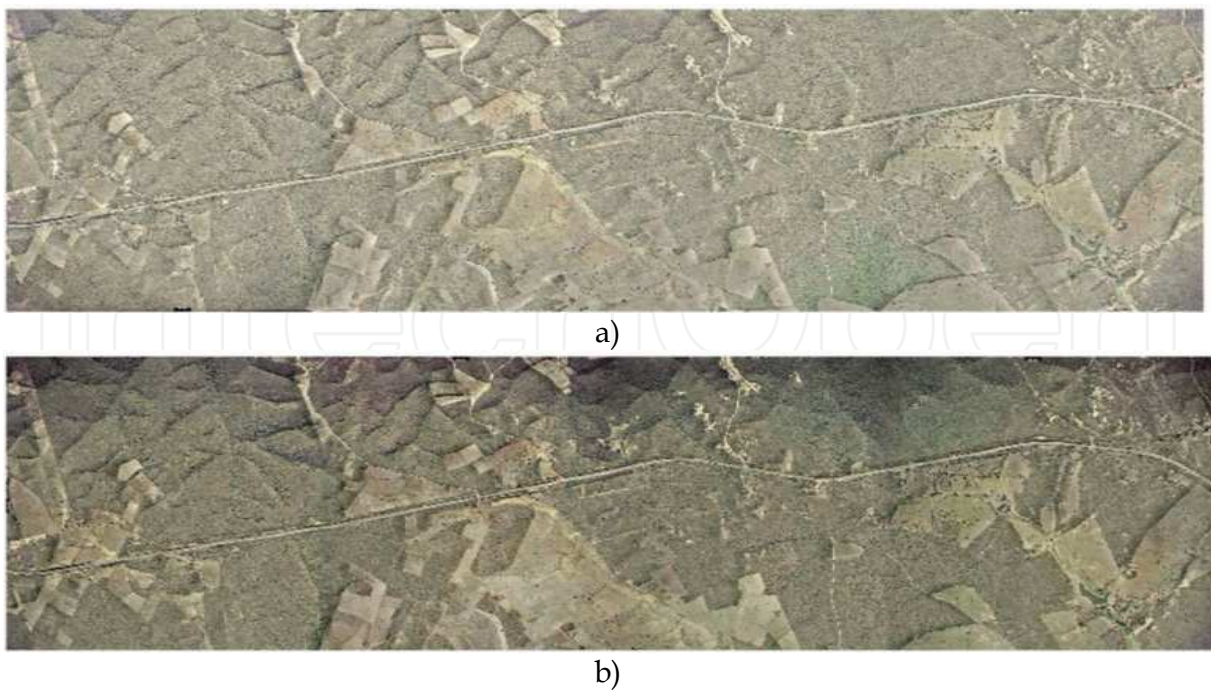


Fig. 18. Mosaics processed with block balancing. a) Photographs pre-processed with masks, b) original photographs. (Photographs: TOPOCART S/ A).

Various tests of mask use in colored aerial photographs were done with rural and urban sceneries in varied scales, and the following was observed:

- The correction works well for images with sceneries without significant variations of texture and tonality. If strong variations occur the masks must be made using an average of three or more photographs.
- The saturated colors in the borders of the original images are not recuperated and a pre processing is need.
- In case the mask is added to the HSV decomposition component V, the recomposed image keeps the tone of the areas of more altered saturated hues (alteration of hue), than when processing with *RGB* bands.

4.3 Correction of full frame

4.3.1 Using Kries method

The general color aspects of an image should be adjusted to a color standard of another image using the Von Kries hypothesis. Similar procedure can also be applied using only color band adjustment present in most graphic processing software, but some practical experience from the operator is necessary.

The image for this kind of color correction must not be saturated. The saturation can be indicated by the presence of too many pixels (peak) at the ends of the histogram, in one or more bands. The histogram of image in Figure 19 shows that it has not color saturation.

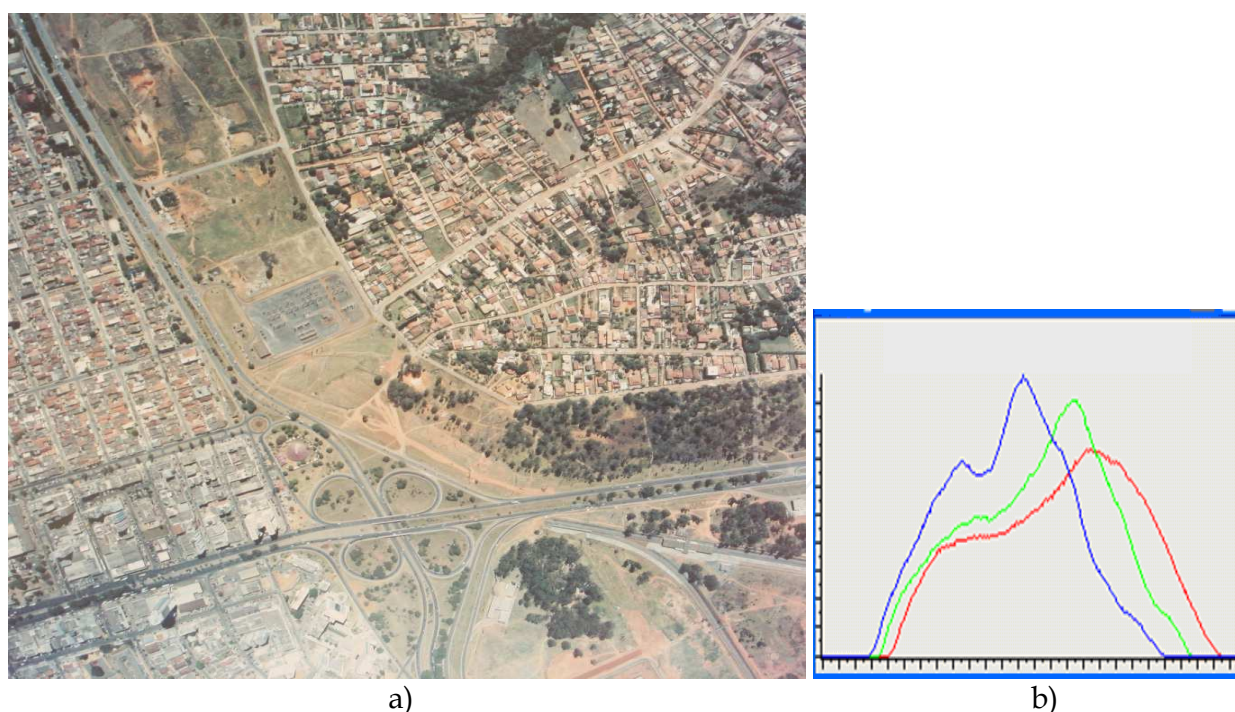


Fig. 19. a) Image example without color saturation, b) Histograms of the RGB bands.

The image in figure 19 was processed with Kries method and using color cast of figure 20 resulting in image showed in figure 21. The coefficients were $KR=1.0759$, $KG=1.1751$, $KB=1.1451$



Fig. 20. Image with a color cast desired.



Fig. 21. Image processed with Kries method.

An example of image with color saturation in the red band is in figure 15a (histogram in figure 22a). The practical solution to eliminate the saturation is to manipulate the luminance or intensity, in order to remove the peak value occurs at 255. In this example firstly was reduced the intensity range using gamma correction setting it to 0.60 and then all the intensity levels was reduced in 10 units. These values were determined by trial and error, but it can also be used image statistics to see the saturation and the need intensity shift. The final result of the histogram of red band is shown in Figure 22b.

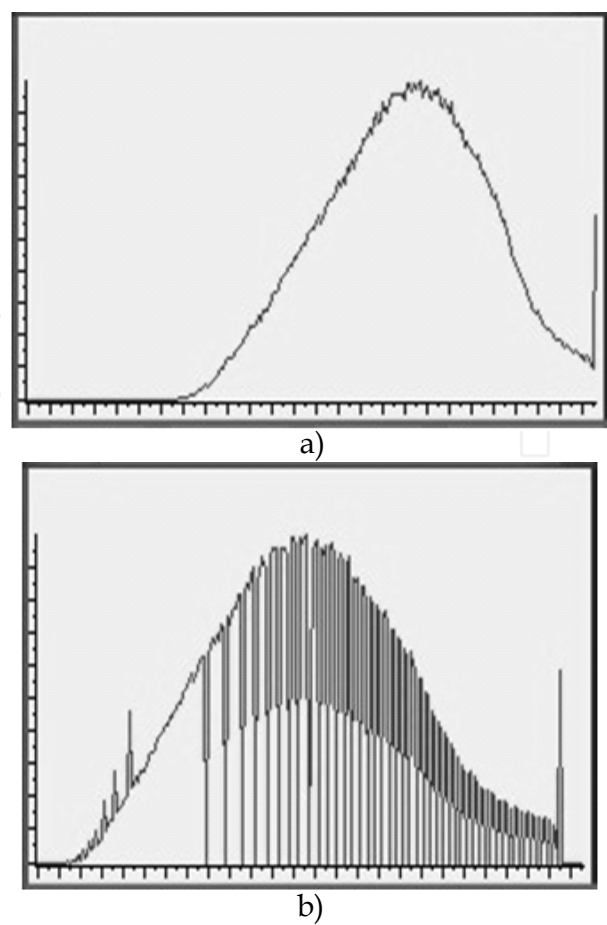


Fig. 22. Histogram of red band figure 15a. a) original saturated, b) After change.

The reconstruction of the RGB image using the new red band results in the image of the figure 23 with a ton greener more real.



Fig. 23. Image of figure 15a with de-saturation of Red band

4.3.2 Using histogram matching

The use of the histogram matching (section 3.4) can also change the color cast of an image. The figure 24b shows the histograms of the image with strong reddish cast to be changed, the figure 24a shows the histograms of the image 21 (template) and figure 24c the final matching histogram. The figure 25 shows the new image with the new histograms.

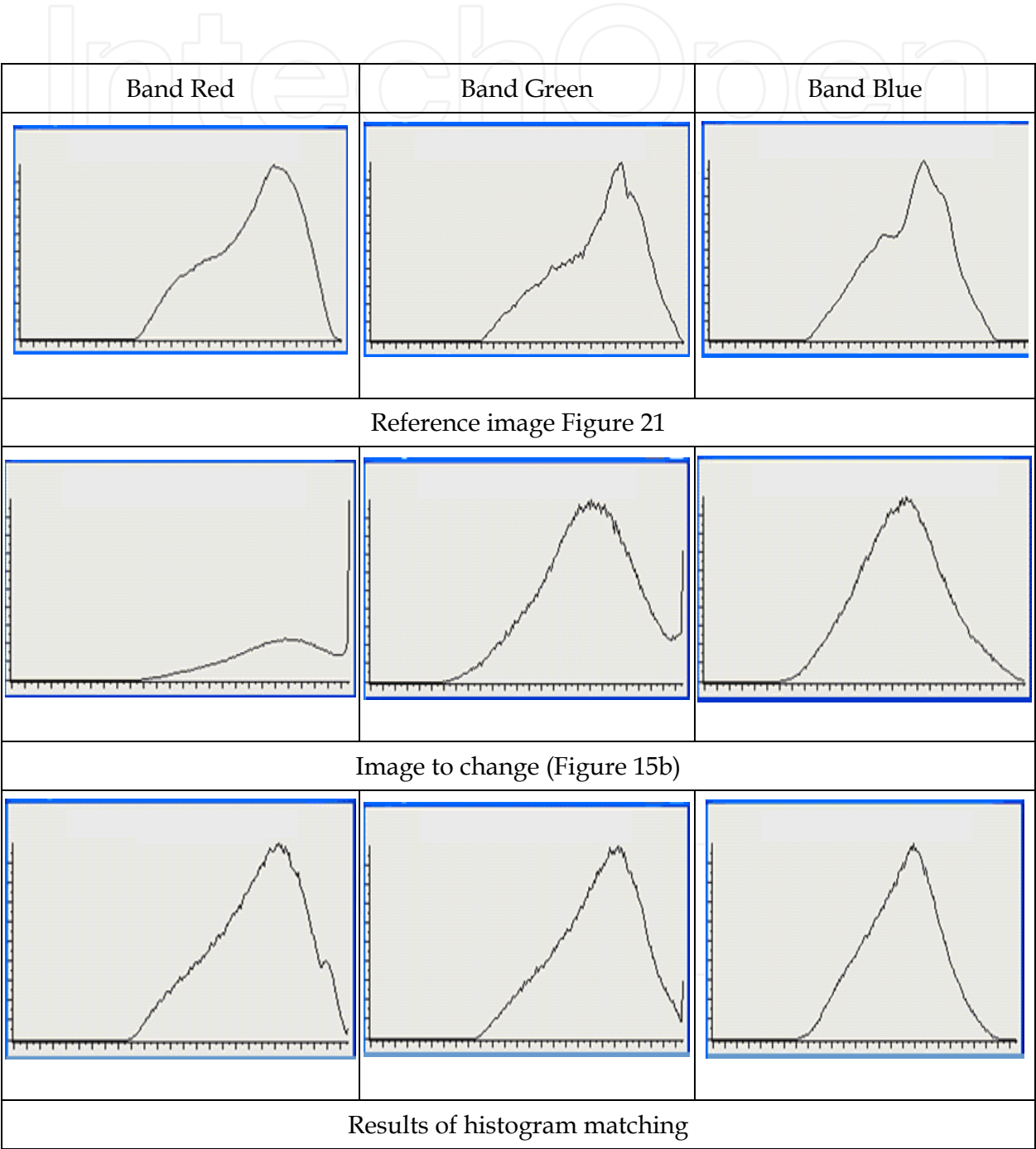


Fig. 24. Histogram matching a) of image template, b) of image to be changed, c) result of the matching



Fig. 25. Final Image of histogram matching on image 15b

The image of figure 15b was also processed with the Kries method using as color standard the same figure 21. The final corrected image (Figure 26) looks similar to image above but more greenish and their histograms have some differences (Figure 27).



Fig. 26. Using Kries method in image 14b

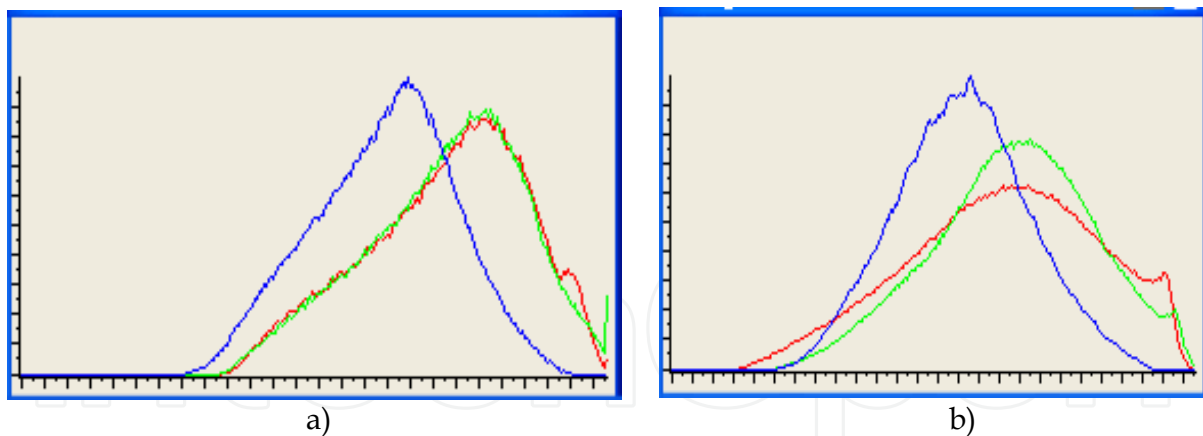


Fig. 27. Histograms after restorations a) of figure 25 by match, b) of figure 26 by Kries.

In a general way these two methods of changing the color cast have minor computational cost than the homogenization of histogram blocks. The best choice and the efficiency in practical applications will be defined by the software implementation. In some cases only one method would give the desired result and in others a combination of both histogram matching and the Kries method would be better fitting.

5. Conclusions

This chapter discusses first, the causes of undesirable color changes in aerial photographs due to atmospheric factors and geometric factors of imaging, like the haze effect, position of the sun and aperture angle of cameras, and in second place some procedures for restorations of those colors.

The combination of the vignetting effect, and of the backscattering of light in haze, results in a non-uniform intensity on photographic frame with an irregular format, different for each photogrammetric flying, so that is not possible to correct it using only the simple model based in the cosine law.

The methods of color restoration in aerial photographs using mask, manipulation of histograms and the Kries hypothesis are discussed and applied with several examples. These methods have minor computational cost than the homogenization among histogram blocks used in commercial softwares.

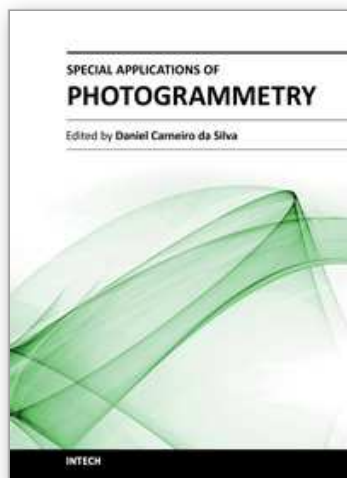
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Photogrammetry is widely accepted as one of the best surveying methods to acquire tridimensional data without direct contact with the object, but its high operational costs in equipment and personnel somewhat limit its application in mapping. However, with the development of digital photogrammetry in the 1990's, it was possible to introduce automated processes and reduce the personnel costs. In the following years, the cost of computer hardware, digital cameras and positioning sensors has been lowering, making photogrammetry more accessible to other engineering fields, such as architecture, archeology and health fields. This book shows the results of the work of researchers from different professional backgrounds, which evaluate the uses of photogrammetry, including issues of the data, processing, as well as the solutions developed for some surveying types that can be extended to many applications.

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